

ARM® Versatile™ Express Beetle IoT Evaluation Board

V2M-Beetle Technical Reference Manual

Confidential - Draft - Alpha



ARM® Versatile™ Express Beetle IoT Evaluation Board

V2M-Beetle Technical Reference Manual

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Release Information

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Product Status

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Web Address

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Conformance Notices

Federal Communications Commission Notice

This device is test equipment and consequently is exempt from part 15 of the FCC Rules under section 15.103 (c).

CE Declaration of Conformity



The system should be powered down when not in use.

It is recommended that ESD precautions be taken when handling Versatile™ Express Express boards.

The motherboard generates, uses, and can radiate radio frequency energy and may cause harmful interference to radio communications. There is no guarantee that interference will not occur in a particular installation. If this equipment causes harmful interference to radio or television reception, which can be determined by turning the equipment off or on, you are encouraged to try to correct the interference by one or more of the following measures:

- Ensure attached cables do not lie across the target board
- Reorient the receiving antenna
- Increase the distance between the equipment and the receiver
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected
- Consult the dealer or an experienced radio/TV technician for help

Note

It is recommended that wherever possible shielded interface cables are used.

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Preface

This preface introduces the *ARM® Versatile™ Express Beetle IoT Evaluation Board V2M-Beetle Technical Reference Manual*.

It contains the following:

- *About this book* on page 7.
- *Feedback* on page 10.

About this book

This book describes the ARM® Versatile™ *Express* (V2M-Beetle) Internet of Things (IoT) evaluation board.

Product revision status

The *rmpn* identifier indicates the revision status of the product described in this book, for example, r1p2, where:

rm Identifies the major revision of the product, for example, r1.

pn Identifies the minor revision or modification status of the product, for example, p2.

Intended audience

This book is written for experienced software developers to aid IoT development using the V2M-Beetle evaluation board.

Using this book

This book is organized into the following chapters:

Chapter 1 Introduction

This chapter introduces the V2M-Beetle evaluation board.

Chapter 2 Hardware Description

This chapter describes the Versatile™ *Express* Express Internet of Things evaluation board hardware.

Chapter 3 Board Configuration and operating modes

This chapter describes board configuration during powerup, loading boot code and test chip programming, CMSIS-DAP programming, and board operating modes.

Chapter 4 Programmers Model

This chapter describes the programmers model of the V2M-Beetle evaluation board.

Appendix A.1 Signal Descriptions

This appendix describes the signals present at the interface connectors of the V2M-Beetle evaluation board.

Appendix B.2 Specifications

This specification contains the electrical specifications of the V2M-Beetle evaluation board.

Appendix C.3 Revisions

This appendix describes the technical changes between released issues of this book.

Glossary

The ARM Glossary is a list of terms used in ARM documentation, together with definitions for those terms. The ARM Glossary does not contain terms that are industry standard unless the ARM meaning differs from the generally accepted meaning.

See the *ARM Glossary* for more information.

Typographic conventions

italic

Introduces special terminology, denotes cross-references, and citations.

bold

Highlights interface elements, such as menu names. Denotes signal names. Also used for terms in descriptive lists, where appropriate.

monospace

Denotes text that you can enter at the keyboard, such as commands, file and program names, and source code.

monospace

Denotes a permitted abbreviation for a command or option. You can enter the underlined text instead of the full command or option name.

monospace italic

Denotes arguments to monospace text where the argument is to be replaced by a specific value.

monospace bold

Denotes language keywords when used outside example code.

<and>

Encloses replaceable terms for assembler syntax where they appear in code or code fragments. For example:

```
MRC p15, 0, <Rd>, <CRn>, <CRm>, <Opcode_2>
```

SMALL CAPITALS

Used in body text for a few terms that have specific technical meanings, that are defined in the *ARM glossary*. For example, IMPLEMENTATION DEFINED, IMPLEMENTATION SPECIFIC, UNKNOWN, and UNPREDICTABLE.

Timing diagrams

The following figure explains the components used in timing diagrams. Variations, when they occur, have clear labels. You must not assume any timing information that is not explicit in the diagrams.

Shaded bus and signal areas are undefined, so the bus or signal can assume any value within the shaded area at that time. The actual level is unimportant and does not affect normal operation.

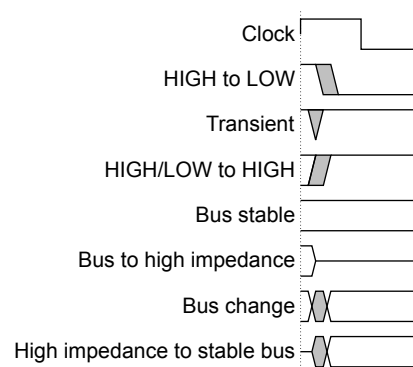


Figure 1 Key to timing diagram conventions

Signals

The signal conventions are:

Signal level

The level of an asserted signal depends on whether the signal is active-HIGH or active-LOW.

Asserted means:

- HIGH for active-HIGH signals.
- LOW for active-LOW signals.

Lowercase n

At the start or end of a signal name denotes an active-LOW signal.

Additional reading

This book contains information that is specific to this product. See the following documents for other relevant information.

ARM publications

- *ARM® IoT Subsystem for Cortex-M® Technical Reference Manual* (ARM DDI 0551)
- *ARM® Cordio® BT4 Radio IP Integration Manual* (ARM DII 0299)
- *Cortex-M™ System Design Kit Technical Reference Manual* (ARM DDI 0479)
- *ARM® PrimeCell Technical Reference Manual Real Time Clock (PL031)* (ARM DDI 0224)

Other publications

- See the Arduino website <https://www.arduino.cc/> for information on Arduino shields.

Feedback

Feedback on this product

If you have any comments or suggestions about this product, contact your supplier and give:

- The product name.
- The product revision or version.
- An explanation with as much information as you can provide. Include symptoms and diagnostic procedures if appropriate.

Feedback on content

If you have comments on content then send an e-mail to errata@arm.com. Give:

- The title *ARM® Versatile™ Express Beetle IoT Evaluation Board V2M-Beetle Technical Reference Manual*.
- The number ARM 100417_0000_00_en_03c.
- If applicable, the page number(s) to which your comments refer.
- A concise explanation of your comments.

ARM also welcomes general suggestions for additions and improvements.

————— **Note** —————

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Chapter 1

Introduction

This chapter introduces the V2M-Beetle evaluation board.

It contains the following sections:

- *1.1 Precautions* on page 1-12.
- *1.2 Ensuring safety* on page 1-13.
- *1.3 Preventing damage* on page 1-14.
- *1.4 About the V2M-Beetle evaluation board* on page 1-15.
- *1.5 Location of components on the V2M-Beetle evaluation board* on page 1-16.

1.1 Precautions

You can take certain precautions to ensure safety and to prevent damage to your V2M-Beetle evaluation board.

1.2 Ensuring safety

There are two alternative power sources for the V2M-Beetle evaluation board, the USB host 5V supply, or two 1.5V AAA batteries.

———— **Warning** ————

Do not use the V2M-Beetle evaluation board near equipment that is sensitive to electromagnetic emissions, for example, medical equipment.

1.3 Preventing damage

The V2M-Beetle evaluation board is intended for use within a laboratory or engineering development environment.

Caution

To avoid damage to the V2M-Beetle evaluation board, observe the following precautions:

- Connect the external power supply to the board before powerup.
 - Never subject the board to high electrostatic potentials. Observe Electrostatic discharge (ESD) precautions when handling any board.
 - Always wear a grounding strap when handling the board.
 - Only hold the board by the edges.
 - Avoid touching the component pins or any other metallic element.
 - Do not use the board near a source of electromagnetic emissions other than Bluetooth radios.
 - Do not fit an expansion shield while power, either 5V USB or AAA batteries, is applied to the V2M-Beetle evaluation board.
-

1.4 About the V2M-Beetle evaluation board

The V2M-Beetle evaluation board provides access to the Beetle test chip to enable hardware and software development for Internet of Things (IoT) applications.

V2M-Beetle evaluation board and Beetle test chip

The Beetle test chip is based on the IoT Subsystem for Cortex[®]-M.

The V2M-Beetle evaluation board provides:

- One Beetle test chip:
 - One IoT Subsystem for Cortex-M that incorporates a Cortex-M3.
 - One ARM Cordio BT4, a Bluetooth Low-Energy radio block.
- Arduino headers that enable fitting of an Arduino-compatible R3 expansion shield:
 - 16 GPIO signals.
 - Power to the expansion shield.
 - I²C interface.
 - SPI interface.
 - UART interface.
 - Six Analog signals from the expansion shield to an ADC on V2M-Beetle evaluation board. The output of the ADC is input to the Beetle test chip.
- A 50Ω on-board antenna.
- One motion sensor:
 - 3-axis orientation and motion sensing.
- One temperature sensor.

Internet of Things (IoT) development

The V2M-Beetle evaluation board, incorporating the Beetle test chip and IoT Subsystem for Cortex-M, enables Internet of Things (IoT) endpoint development with expansion by fitting an Arduino-compatible R3 expansion shield.

1.5 Location of components on the V2M-Beetle evaluation board

The following figures show the physical layout of the V2M-Beetle evaluation board.

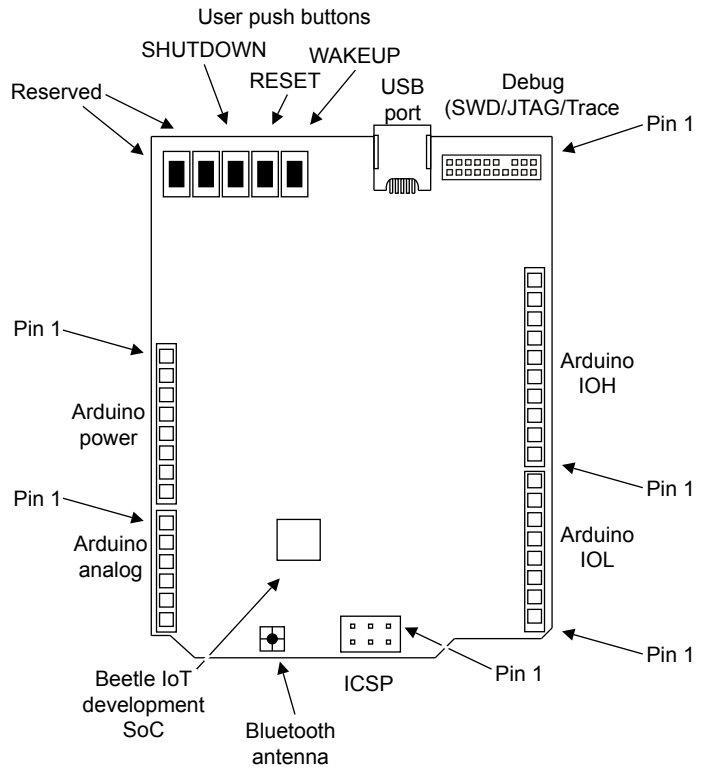


Figure 1-1 V2M-Beetle evaluation board upper face

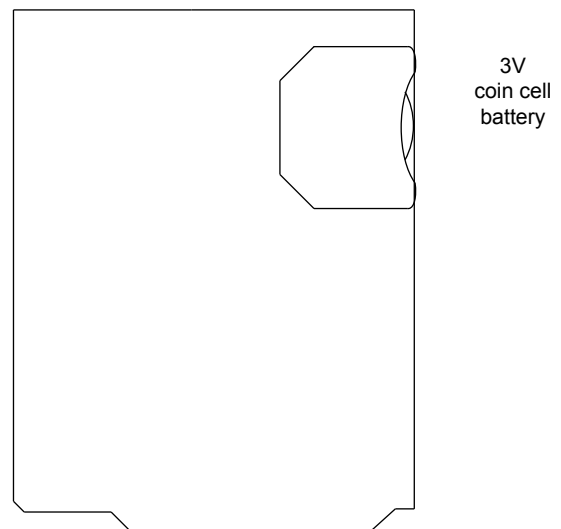


Figure 1-2 V2M-Beetle evaluation board lower face

Chapter 2

Hardware Description

This chapter describes the Versatile™ *Express* Express Internet of Things evaluation board hardware.

It contains the following sections:

- *2.1 Overview of the V2M-Beetle evaluation board on page 2-18.*
- *2.2 Architecture of the Beetle test chip on page 2-21.*
- *2.3 Beetle test chip GPIO interface on page 2-24.*
- *2.4 Clocks on page 2-27.*
- *2.5 Resets on page 2-28.*
- *2.6 USB interface on page 2-30.*
- *2.7 SPI ADC interface on page 2-32.*
- *2.8 Interrupts on page 2-33.*
- *2.9 Cordio® BT4 Bluetooth Low-Energy radio and antenna on page 2-35.*
- *2.10 V2M-Beetle evaluation board power on page 2-36.*
- *2.11 Beetle test chip power management on page 2-37.*
- *2.12 Board peripherals on page 2-39.*
- *2.13 Debug and trace on page 2-40.*

2.1 Overview of the V2M-Beetle evaluation board

The hardware infrastructure of the V2M-Beetle evaluation board supports IoT endpoint development by providing access to the IoT development chip, the Beetle test chip.

The following figure shows the hardware infrastructure of the V2M-Beetle evaluation board.

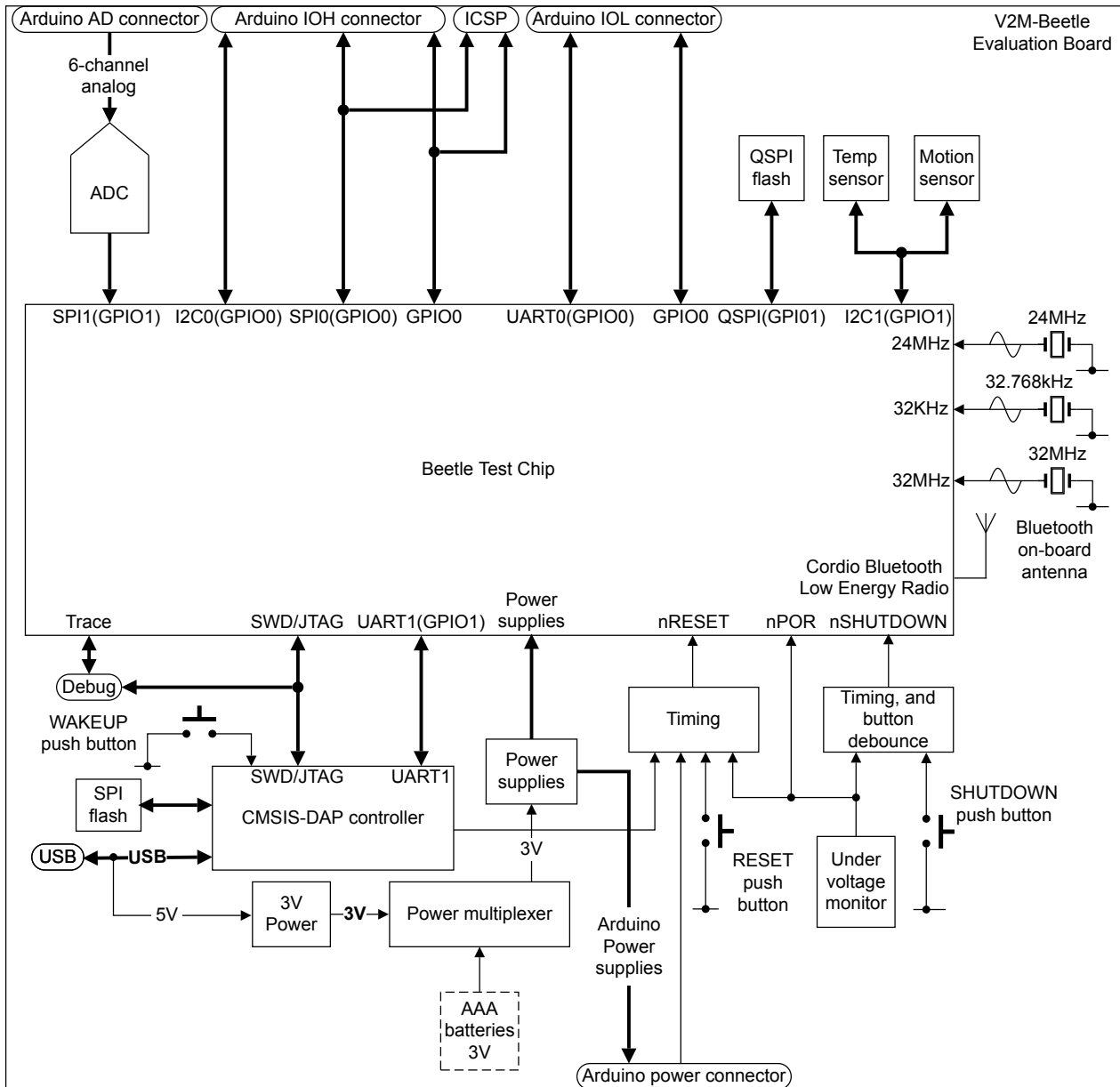


Figure 2-1 V2M-Beetle evaluation board system architecture with fitted Arduino board

The V2M-Beetle evaluation board contains the following components and interfaces:

- Beetle test chip:
 - IoT Subsystem for Cortex-M.
 - RF port that connects to the 50Ω on-board antenna on the V2M-Beetle evaluation board.
 - Cortex-M3, part of the IoT Subsystem for Cortex-M
- USB port and CMSIS-DAP controller that provides programming and debug access:

- Drag-and-drop system software image programming.
- CMSIS-DAP software debug.
- Virtual UART access over USB.
- Reset over USB and from external debugger.
- Debug port:
 - Serial Wire Debug (SWD).
 - 4-bit trace.
 - P-JTAG debug.
 - Beetle test chip debug when the CMSIS-DAP controller is powered down.
- SPI flash, which is associated with the CMSIS-DAP.
- QSPI flash:
 - 256K alternative bootup memory for the Cortex-M3, an alternative to the embedded flash (eFlash) in the Beetle test chip.
- 32kHz crystal oscillator:
 - Drives the Cordio BT4 Bluetooth RF block in the Beetle test chip.
 - Is available as an input to the test chip clock prescaler circuitry.
- 32MHz oscillator:
 - Drives the Cordio BT4 Bluetooth RF block in the Beetle test chip.
- 24MHz oscillator:
 - Drives the clock PLL in the Beetle test chip.
- Analog to Digital Converter (ADC):
 - 6-channel Analog input from the Arduino AD connector.
 - Analog reference voltage from the Arduino IOH connector.
 - SPI output that connects to the SPI0 interface in the Beetle test chip.

————— **Note** —————

The ADC is only available when the Arduino power is enabled. When the Arduino power is not enabled, configure the ADC pin on the Beetle test chip as GPIO pins to save power.

- Temperature and motion sensors:
 - These sensors send data to the I2C1 interface in the Beetle test chip.
- Two power sources:
 - External 5V power through the USB port.
 - Two AAA batteries (optional).

————— **Note** —————

The choice of power source determines which operating and power modes are available to the board.

- Board shutdown system that resets the Cortex-M3 and causes the system to enter the shutdown sequence. The shutdown sources are:
 - User shutdown push button.
 - On-board under-voltage monitor.
- Board reset system that resets all hardware on the board except the eFlash power controller. The reset sources are:
 - Power on RC delay.
 - User reset push button.
 - CMSIS-DAP reset over USB.
 - Reset signal from Arduino power connector.
 - Reset signal from external debugger.
- Arduino AD connector that carries six Analog signals to the ADC.
- Arduino IOL connector that carries:
 - Six GPIO signals from the Beetle test chip.
 - Two multiplexed GPIO-UART0 signals from the Beetle test chip.
- Arduino IOH connector that carries:

- Two GPIO signals from the Beetle test chip.
- Four multiplexed GPIO-SPI1 signals from the Beetle test chip.
- Two multiplexed GPIO-I2C signals from the Beetle test chip.
- Arduino power connector:
 - 5V and 3V power to the fitted expansion shield.
 - 3V3 reference for the I/O digital pins.
 - Reset signal that connects to the CMSIS-DAP controller.
 - Raw reference voltage for local voltage regulator on the expansion shield.

Note

The V2M-Beetle evaluation board:

- Accepts Arduino-compatible R3 expansion shields.
- Outputs signals at 3V3.

-
- ICSP connector:
 - Enables In-Circuit Serial Programming.

See the *ARM® IoT Subsystem for Cortex-M® Technical Reference Manual* for more information on the IoT Subsystem for Cortex-M.

2.2 Architecture of the Beetle test chip

The test chip provides facilities to aid Internet of Things endpoint development.

The following figure shows the architecture of the Beetle test chip.

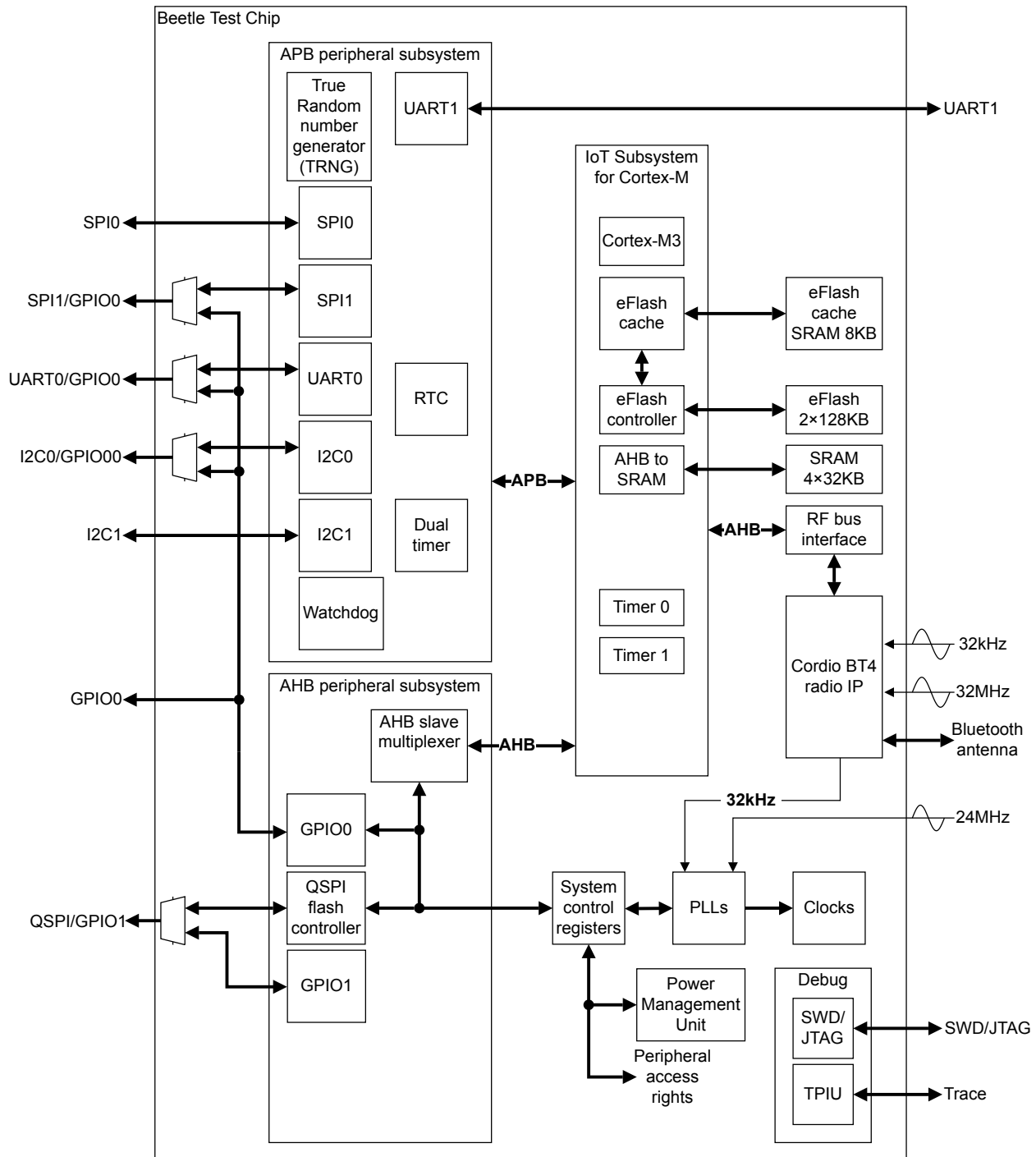


Figure 2-2 Architecture of the test chip

The Beetle test chip contains the following components and interfaces:

- IoT Subsystem for Cortex-M:

- Cortex-M3 processor.
- Two independent timers.
- SRAM controller, part of the SRAM memory subsystem.
- eFlash memory subsystem:
 - eFlash controller, in the IoT Compute subsystem.
 - eFlash cache, in the IoT Compute subsystem. It caches instructions and data that are stored in the eFlash.
 - 2×128KB eFlash memory.
- SRAM memory subsystem:
 - 4×32KB.
- APB peripheral subsystem:
 - SPI interface, *SPI0*, that connects to the ADC on the V2M-Beetle evaluation board.
 - SPI interface, *SPI1*, that connects to the *IOH* Arduino header on the V2M-Beetle evaluation board.
 - UART interface, *UART0*, that connects to the *IOL* Arduino header. Interface *UART0* connects to the *UART0* connector on the V2M-Beetle evaluation board.
 - UART interface, *UART1*, that connects to the CMSIS-DAP virtual UART port on the V2M-Beetle evaluation board.
 - I²C interface, *ITC0*, that connects to the *I2C0* connector on the V2M-Beetle evaluation board.
 - I²C interface, *ITC1*, that connects to the *I2C1* connector on the V2M-Beetle evaluation board.
 - Watchdog timer.
 - Dual-timer.
 - *Real-time clock* (RTC).
 - True Random number generator (TRNG).

————— **Note** —————

- Interfaces *SPI1*, *UART0*, and *ITC0* are multiplexed with GPIO signals. The selected signals at the output of the multiplexers drive the board connectors.
- The SPI interfaces natively support only 8-bit mode.

-
- AHB peripheral subsystem:
 - GPIO interface that connects to the Arduino headers. Some I/O are multiplexed with *SPI1*, *UART0*, and *ITC0* in the APB peripheral subsystem and the multiplexed outputs connect to the Arduino headers.
 - QuadSPI flash controller. The controller outputs are multiplexed with some of the GPIO signals and these multiplexed outputs connect to the *QuadSPI* flash memory on the V2M-Beetle evaluation board.

————— **Note** —————

See [2.3 Beetle test chip GPIO interface on page 2-24](#) for a full description of the GPIO multiplexing scheme.

-
- System control:
 - The system control registers provide power management, clock configuration and control, and peripheral access permission configuration.
 - Bluetooth radio:
 - ARM Cordio BT4 radio, a Bluetooth Low Energy (BLE) RF block.
 - Host Controller Interface (HCI) to the Cortex-M3.
 - Imports a 32MHz signal and a 32kHz signal from crystal oscillators on the V2M-Beetle evaluation board. It exports the 32kHz clock signal to other systems in the Beetle test chip.
 - Debug:
 - 4-bit trace port from the *Trace Port Interface Unit* (TPIU) in the Beetle test chip.
 - SWD/JTAG port.

See *ARM® IoT Subsystem for Cortex-M® Technical Reference Manual* for more information on the IoT Subsystem for Cortex-M and the following:

- Timers.
- eFlash memory system.
- SRAM memory system.

See *Cortex-M™ System Design Kit Technical Reference Manual* for more information on the following:

- GPIO interfaces.
- Watchdog.
- UARTs.
- Dual timer.

See *ARM® Cordio® BT4 Radio IP Integration Manual* for more information on the Cordio BT4 Bluetooth Low Energy RF block.

2.3 Beetle test chip GPIO interface

The Beetle test chip multiplexes general-purpose I/O (GPIO) with SPI, UART, I²C, and QSPI signals.

The GPIO registers, GPIO0ALTFUNCSET, GPIO1ALTFUNCSET, GPIO0ALTFUNCCLR, and GPIO1ALTFUNCCLR, select the multiplexed signals. The following table shows the GPIO multiplexing scheme including the connectivity of the multiplexed signals. You must select the alternative functions for normal and full operation of the test chip.

Table 2-1 Beetle test chip multiplexed GPIO signals

GPIO default function (AHB peripheral subsystem)	Alternative function	Connectivity	Source of alternative function on test chip
GPIO0[0]	UART0 RxD (In)	Arduino IOL header pin 1	APB peripheral subsystem
GPIO0[1]	UART0 TxD (Out)	Arduino IOL header pin 2	
GPIO0[2]	-	Arduino IOL header pin 3	-
GPIO0[3]		Arduino IOL header pin 4	
GPIO0[4]		Arduino IOL header pin 5	
GPIO0[5]		Arduino IOL header pin 6	
GPIO0[6]		Arduino IOL header pin 7	
GPIO0[7]		Arduino IOL header pin 8	
GPIO0[8]		Arduino IOH header pin 1	
GPIO0[9]		Arduino IOH header pin 2	
GPIO0[10]	SPI0 nSS[0]	Arduino IOH header pin 3	APB peripheral subsystem
GPIO0[11]	SPI0 MOSI (Out)	Arduino IOH header pin 4	
GPIO0[12]	SPI0 MISO (In)	Arduino IOH header pin 5	
GPIO0[13]	SPI0 SCK (Out)	Arduino IOH header pin 6	
GPIO0[14]	I2C0 Data (SDA)	Arduino IOH header pin 9	
GPIO0[15]	I2C0 Clock (SCL)	Arduino IOH header pin 10	
GPIO1[0]	UART1 RxD (In)	CMSIS-DAP controller	
GPIO1[1]	UART1 TxD (Out)		
GPIO1[2]	SPI1 nSS[0]	ADC	
GPIO1[3]	SPI1 MOSI (Out)		
GPIO1[4]	SPI1 MISO (In)		
GPIO1[5]	SPI1 SCK (Out)		
GPIO1[6]	I2C1 Data (SDA)	Temperature and motion sensors	
GPIO1[7]	I2C1 Clock (SCL)		
GPIO1[8]	I2C1 Interrupt		

Table 2-1 Beetle test chip multiplexed GPIO signals (continued)

GPIO default function (AHB peripheral subsystem)	Alternative function	Connectivity	Source of alternative function on test chip
GPIO1[9]	QSPI CS1	QSPI flash	AHB peripheral subsystem
GPIO1[10]	QSPI IOF0		
GPIO1[11]	QSPI IOF1		
GPIO1[12]	QSPI IOF2		
GPIO1[13]	QSPI IOF3		
GPIO1[14]	QSPI IOF4		
GPIO1[15]	-	Arduino power enable system on V2M-Beetle evaluation board.	APB peripheral subsystem

Table 2-2 Beetle test chip multiplexed GPIO signals

GPIO default function (AHB peripheral subsystem)	Alternative function	Connectivity	Source of alternative function on test chip
GPIO0[0]	UART0 RxD (In)	Arduino IOL header pin 1	APB peripheral subsystem
GPIO0[1]	UART0 TxD (Out)	Arduino IOL header pin 2	
GPIO0[2]	-	Arduino IOL header pin 3	
GPIO0[3]		Arduino IOL header pin 4	
GPIO0[4]		Arduino IOL header pin 5	
GPIO0[5]		Arduino IOL header pin 6	
GPIO0[6]		Arduino IOL header pin 7	
GPIO0[7]		Arduino IOL header pin 8	
GPIO0[8]		Arduino IOH header	
GPIO0[9]			
GPIO0[10]	SPI0 nSS[0]		APB peripheral subsystem
GPIO0[11]	SPI0 MOSI (Out)		
GPIO0[12]	SPI0 MISO (In)		
GPIO0[13]	SPI0 SCK (Out)		
GPIO0[14]	I2C0 Data (SDA)		
GPIO0[15]	I2C0 Clock (SCL)		
GPIO1[0]	UART1 RxD (In)	CMSIS-DAP controller	
GPIO1[1]	UART1 TxD (Out)		
GPIO1[2]	SPI1 nSS[0]	ADC	
GPIO1[3]	SPI1 MOSI (Out)		
GPIO1[4]	SPI1 MISO (In)		
GPIO1[5]	SPI1 SCK (Out)		
GPIO1[6]	I2C1 Data (SDA)		Temperature and motion sensors
GPIO1[7]	I2C1 Clock (SCL)		
GPIO1[8]	I2C1 Interrupt		

Table 2-2 Beetle test chip multiplexed GPIO signals (continued)

GPIO default function (AHB peripheral subsystem)	Alternative function	Connectivity	Source of alternative function on test chip
GPIO1[9]	QSPI CS1	QSPI flash	AHB peripheral subsystem
GPIO1[10]	QSPI IOF0		
GPIO1[11]	QSPI IOF1		
GPIO1[12]	QSPI IOF2		
GPIO1[13]	QSPI IOF3		
GPIO1[14]	QSPI IOF4		
GPIO1[15]	-	Arduino power enable system on V2M-Beetle evaluation board.	APB peripheral subsystem

Related concepts

[4.6 GPIO registers on page 4-58.](#)

Related references

[Arduino IOL connector on page Appx-A-119.](#)

[Arduino IOH connector on page Appx-A-118.](#)

2.4 Clocks

The V2M-Beetle evaluation board contains 24MHz and 32kHz crystal oscillators which drive the systems on the board and in the Beetle test chip.

Overview of clocks

The following figure shows the V2M-Beetle evaluation board and test chip system clocks.

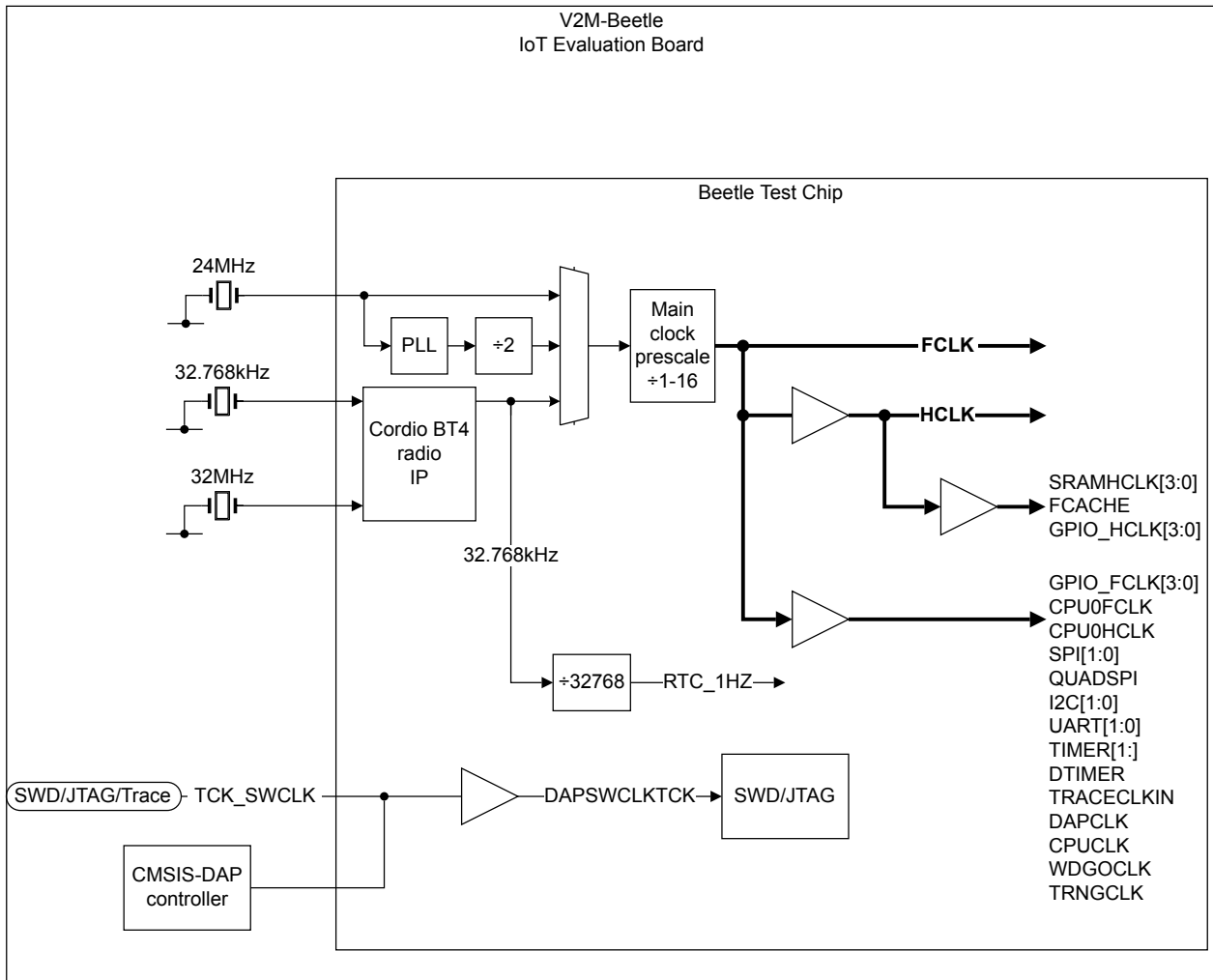


Figure 2-3 Beetle test chip clocks

System control register MAINCLK controls the input clock multiplexer and the output prescaler. The input is **CLK24MHZ** and the default prescaler setting is *bypass prescaler*, that is, no frequency division. The DAPlink chip provides the debug clock **TCK_SWCLK**.

The debug clock, **TCK_SWCLK**, has two sources. It can come from the debug connector or from the CMSIS-DAP controller.

Related references

[4.7.9 MAINCLK on page 4-74.](#)

2.5 Resets

The reset system on the V2M-Beetle evaluation board provides one reset push button, one shutdown push button, and two reset signals to the Beetle test chip.

The following figure shows the reset system.

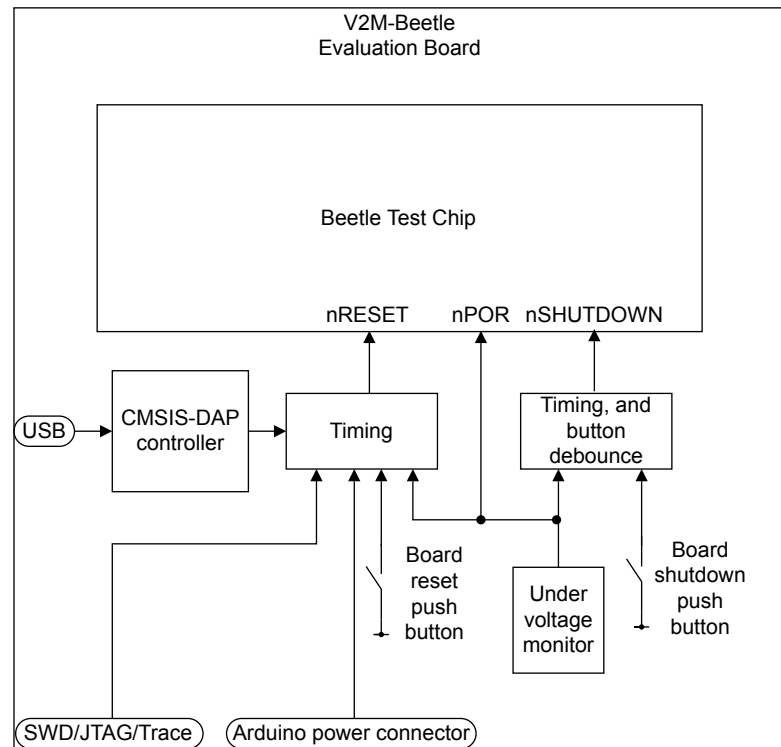


Figure 2-4 V2M-Beetle evaluation board resets

The test chip reset and shutdown signals are:

nPOR

This reset operates during the powerup process when the board voltage rises above 2V7.

nRESET

Performs a hardware reset of the test chip. It has the following sources:

- *RESET* push button.
- CMSIS-DAP reset over USB.
- Reset from external debugger.
- Expansion shield.
- The under-voltage monitor, when the board voltage rises above 2V7 during the powerup process. Timing circuitry synchronizes this signal with **nPOR**.

nSHUTDOWN

Powers down the test chip. It has the following sources:

- Under-voltage monitor, when the board voltage falls below 2V7.
- *SHUTDOWN* push button.

Caution

ARM recommends pressing the *SHUTDOWN* push button before disconnecting the power source to avoid the possibility of damaging the eFlash memory in the test chip.

The following figure shows the powerup and powerdown timing sequences.

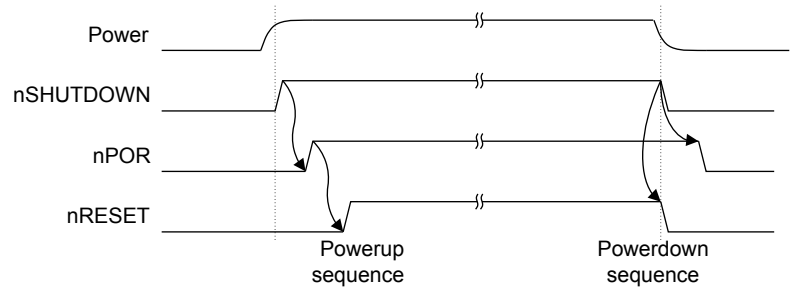


Figure 2-5 Powerup and powerdown timing sequences

The following figure shows the reset sequence where one of the reset sources generates signal **nRESET** to the test chip.

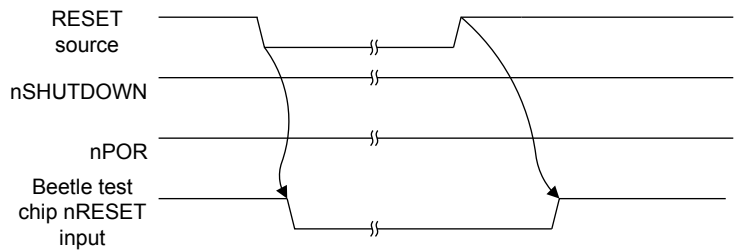


Figure 2-6 Reset sequence

Note

- Signal **RESET source** represents the active reset source generating the reset sequence.
- For resets generated by the *RESET* button, the diagram shows the debounced push button signal.

2.6 USB interface

The V2M-Beetle evaluation board provides one USB port for configuration and debug.

The following figure shows the V2M-Beetle evaluation board USB interface.

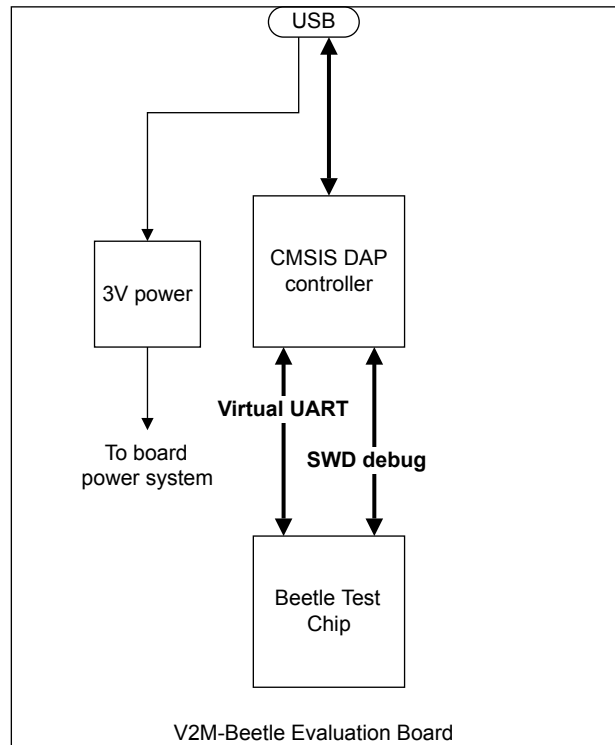


Figure 2-7 USB interface

The USB port enables:

- Virtual UART over USB.
- External 5V power.
- CMSIS-DAP reset and debug.
- Drag-and-drop software image programming.

Updating the CMSIS-DAP image

The following procedure updates the CMSIS-DAP image using a host computer running Microsoft Windows.

1. Remove the USB host cable from the V2M-Beetle evaluation board.
2. Press and hold the ISP button while reinserting the USB host cable.
3. The host computer mounts a new drive, labeled *CRP DISABLD*.
4. Drag and drop the CMSIS-DAP binary file onto the new drive.
5. When copying the new file is complete, remove and then reinsert the USB host cable.

————— **Note** —————

- The eFlash in the test chip and QSPI Flash on the V2M-Beetle evaluation board require different firmware.
- See *Beetle_mbed_webpage_TBD* for more information.

Related references

1.5 Location of components on the V2M-Beetle evaluation board on page 1-16.

A.1.3 USB connector on page Appx-A-123.

2.7 SPI ADC interface

The V2M-Beetle evaluation board Arduino AD connector carries six Analog signals to the Analog to Digital Converter (ADC). The ADC digital output connects to the SPI1 interface on the Beetle test chip.

The following figure shows the V2M-Beetle evaluation board SPI ADC interface.

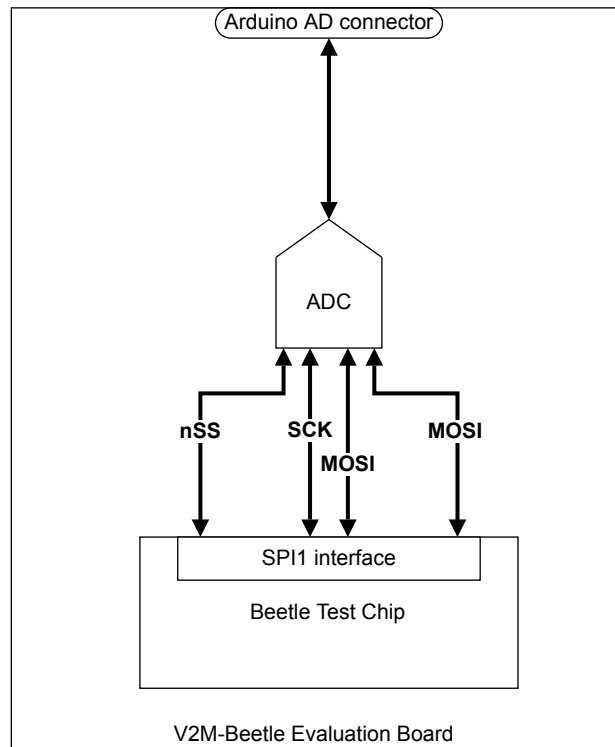


Figure 2-8 SPI ADC interface

The characteristics of the ADC are:

- Part number: Texas Instruments ADC128S052.
- Resolution: 12-bit.
- Sample rate: 200-500 kSPS.
- Input range: 0-5V.
- Type: Successive-Approximation Register (SAR).

Note

The expansion shield must be enabled to enable the ADC. When the expansion shield power supply enable signal, GPIO1[15], is not enabled, that is, set HIGH, the ADC is not available on the SPI1 interface.

Related concepts

[2.3 Beetle test chip GPIO interface on page 2-24.](#)

Related references

[1.5 Location of components on the V2M-Beetle evaluation board on page 1-16.](#)

[Arduino IOH connector on page Appx-A-118.](#)

2.8 Interrupts

The IoT Compute subsystem controller implements a nested vector interrupt controller.

The following table shows the mapping of the interrupt signals from the test chip.

Table 2-3 test chip interrupts and their sources on the V2M-Beetle evaluation board

Interrupt	Source
NMI	Watchdog
IRQ0	UART0
IRQ1	Reserved
IRQ2	UART1
IRQ3	I2C0
IRQ4	I2C1
IRQ5	RTC
IRQ6	GPIO0 combined interrupt
IRQ7	GPIO1 combined interrupt
IRQ8	Timer 0
IRQ9	Timer 1
IRQ10	Dual-timer
IRQ11	SPI0
IRQ12	UART overflow
IRQ13	SPI1
IRQ14	QSPI
IRQ15	Reserved
IRQ16	GPIO 0/1 pin 0
IRQ17	GPIO 0/1 pin 1
IRQ18	GPIO 0/1 pin 2
IRQ19	GPIO 0/1 pin 3
IRQ20	GPIO 0/1 pin 4
IRQ21	GPIO 0/1 pin 5
IRQ22	GPIO 0/1 pin 6
IRQ23	GPIO 0/1 pin 7
IRQ24	GPIO 0/1 pin 8
IRQ25	GPIO 0/1 pin 9
IRQ26	GPIO 0/1 pin 10
IRQ27	GPIO 0/1 pin 11
IRQ28	GPIO 0/1 pin 12
IRQ29	GPIO 0/1 pin 13
IRQ30	GPIO 0/1 pin 14
IRQ31	GPIO 0/1 pin 15

Table 2-3 test chip interrupts and their sources on the V2M-Beetle evaluation board (continued)

Interrupt	Source
IRQ32	System error (eFlash cache)
IRQ33	eFlash
IRQ34	LLC_TXCMDIRQ (Cordio)
IRQ35	LLC_TXEVTIRQ (Cordio)
IRQ36	LLC_TXDMA0IRQ (Cordio)
IRQ37	LLC_TXDMA1IRQ (Cordio)
IRQ38	LLC_RXCMDIRQ (Cordio)
IRQ39	LLC_RXEVTIRQ (Cordio)
IRQ40	LLC_RXDMA0IRQ (Cordio)
IRQ41	LLC_RXDMA1IRQ (Cordio)
IRQ42	GPIO2 (Cordio)
IRQ43	GPIO3 (Cordio)
IRQ44	True Random Number Generator (TRNG)

2.9 Cordio® BT4 Bluetooth Low-Energy radio and antenna

The V2M-Beetle evaluation board provides an on-board antenna that connects to the Bluetooth Low-Energy (BLE) RF block in the test chip.

The following figure shows the V2M-Beetle evaluation board Cordio BT4 Bluetooth low energy radio and antenna system.

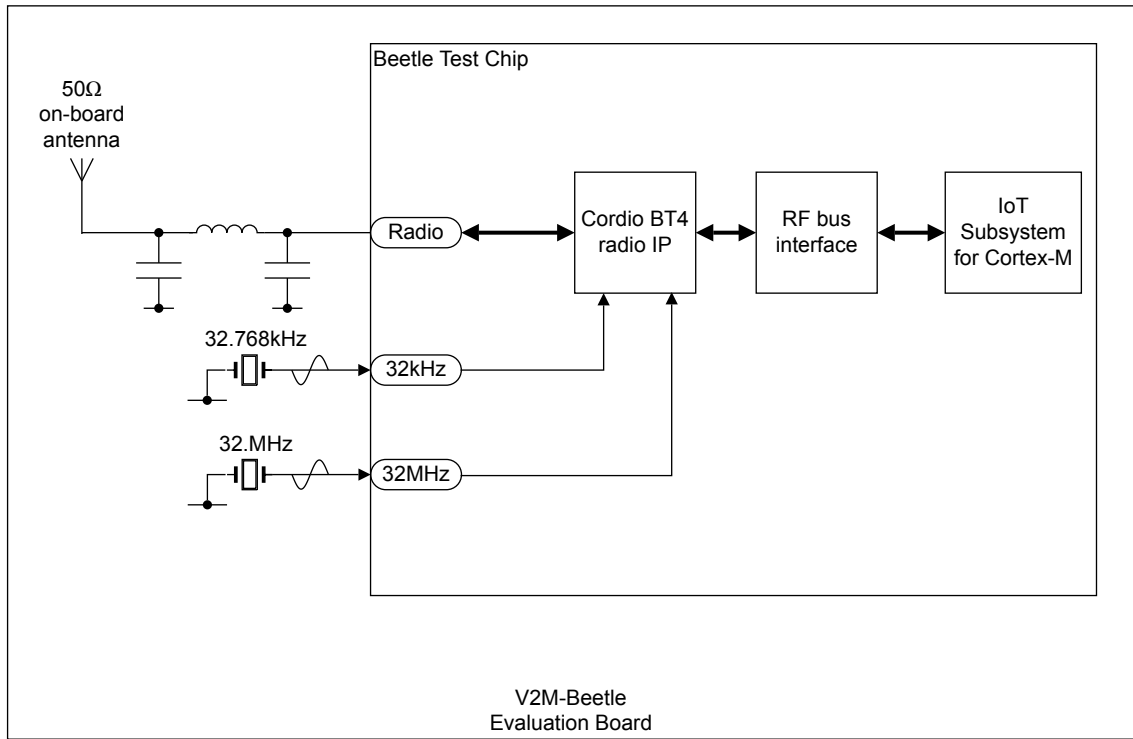


Figure 2-9 Cordio BT4 Bluetooth low energy radio and antenna system

Related references

[1.5 Location of components on the V2M-Beetle evaluation board on page 1-16.](#)

2.10 V2M-Beetle evaluation board power

The V2M-Beetle evaluation board has two alternative power sources, an external 5V USB supply, and on-board AAA batteries.

The following figure shows the V2M-Beetle evaluation board power scheme.

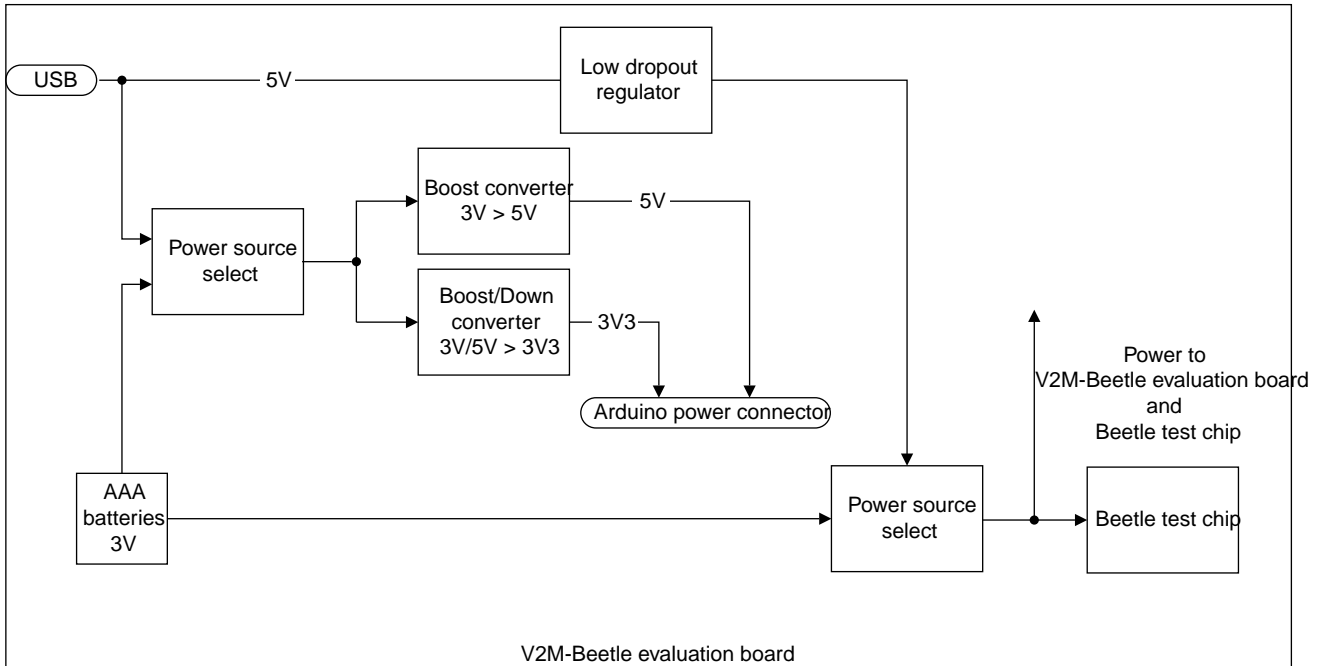


Figure 2-10 V2M-Beetle evaluation board power scheme

USB 5V

When the 5V USB power is connected, the switch automatically selects this power supply and overrides the AAA batteries.

Two AAA batteries (3V)

For use when extended battery operation is required, or if battery operation is required during expansion shield usage.

Note

The choice of power source determines the possible operating modes of the board. See [3.2 Operating modes on page 3-43](#)

Related references

[1.5 Location of components on the V2M-Beetle evaluation board on page 1-16.](#)

2.11 Beetle test chip power management

The test chip provides sleep states of different levels of power consumption to support power management.

This section contains the following subsections:

- [2.11.1 Active state on page 2-37.](#)
- [2.11.2 Sleep state on page 2-37.](#)
- [2.11.3 Deep sleep state on page 2-38.](#)
- [2.11.4 Powerdown sleep state on page 2-38.](#)

2.11.1 Active state

The active state is the fully operational mode of the Beetle test chip.

The characteristics of the active state of the test chip are:

- Processor clocks **HCLK** and **FCLK** are on.
- System AHB clock **HCLK** is on.
- Peripheral clock (APB) operates during transfers.

System control registers configure the peripheral clocks in the active state.

AHBCLKCFG0SET

This register enables AHB peripheral clocks **FCLK** and **HCLK** to GPIO1 and GPIO0 interfaces that connect to the Arduino IOH and IOL connectors.

AHBCLKCFG0CLR

This register disables AHB peripheral clocks **FCLK** and **HCLK** to GPIO1 and GPIO0 interfaces that connect to the Arduino IOH and IOL connectors.

APBCLKCFG0SET

This register enables the APB peripheral clocks that connect to the Arduino IOH and IOL connectors, and to components on the V2M-Beetle evaluation board.

APBCLKCFG0CLR

This register disables the APB peripheral clocks that connect to the Arduino IOH and IOL connectors and, to components on the V2M-Beetle evaluation board.

2.11.2 Sleep state

The sleep state is one of the states that provides power-saving in the Beetle test chip.

The characteristics of the sleep state of the test chip are:

- Processor clock **FCLK** is on.
- Processor clock **HCLK** is off.
- System bus clock **HCLK** is off except when the Cordio BT4 Bluetooth RF block requests transfers.
- Peripheral clock (APB) operates during transfers.

System control registers configure the peripheral clocks in the sleep state:

AHBCLKCFG1SET

This register enables AHB peripheral clocks **FCLK** and **HCLK** to GPIO1 and GPIO0 interfaces that connect to the Arduino IOH and IOL connectors.

AHBCLKCFG1CLR

This register disables AHB peripheral clocks **FCLK** and **HCLK** to GPIO1 and GPIO0 interfaces that connect to the Arduino IOH and IOL connectors.

APBCLKCFG1SET

This register enables the APB peripheral clocks that connect to the Arduino IOH and IOL connectors, and to components on the V2M-Beetle evaluation board.

APBCLKCFG1CLR

This register disables the APB peripheral clocks that connect to the Arduino IOH and IOL connectors and, to components on the V2M-Beetle evaluation board.

2.11.3 Deep sleep state

The deep sleep state is one of the states that provides power-saving in the Beetle test chip.

System control register SLEEPCFG configures the deep sleep state of the test chip. The characteristics of the deep sleep state are:

- Processor clocks **FCLK** and **HCLK** are off.
- System bus clock **HCLK** is off except when the Cordio BT4 Bluetooth RF block requests transfers.
- SRAM can be put into state retention mode.

System control registers configure the deep sleep state:

MAINCLK

This register can enable the main clocks, **FCLK** and **HCLK**, in the deep sleep state.

SLEEPCFG

This register controls power modes, retention modes, and other settings for eFlash, eFlash cache SRAM, SRAM, and Cordio.

AHBCLKCFG2SET

This register enables AHB peripheral clocks **FCLK** and **HCLK** to GPIO1 and GPIO0 interfaces that connect to the Arduino IOH and IOL connectors.

AHBCLKCFG2CLR

This register disables AHB peripheral clocks **FCLK** and **HCLK** to GPIO1 and GPIO0 interfaces that connect to the Arduino IOH and IOL connectors.

APBCLKCFG2SET

This register enables the APB peripheral clocks that connect to the Arduino IOH and IOL connectors, and to components on the V2M-Beetle evaluation board.

APBCLKCFG2CLR

This register disables the APB peripheral clocks that connect to the Arduino IOH and IOL connectors and, to components on the V2M-Beetle evaluation board.

2.11.4 Powerdown sleep state

The powerdown sleep state provides the maximum available power-saving in the Beetle test chip.

The characteristics of the deep sleep state are:

- Processor clocks **FCLK** and **HCLK** are off.
- System bus clock **HCLK** is off except when the Cordio Bluetooth RF block requests transfers.
- SRAM is powered down. It can be put into state retention mode.
- Peripherals, except GPIO, can be powered or powered down. If not powered down, the peripherals retain their state during test chip powerdown sleep state.
- Debug not operational.
- Wake up with interrupts or reset.

System control registers configure the powerdown sleep state:

AHBCLKCFG2SET

This register enables AHB peripheral clocks **FCLK** and **HCLK** to GPIO1 and GPIO0 interfaces that connect to the Arduino IOH and IOL connectors.

AHBCLKCFG2CLR

This register disables AHB peripheral clocks **FCLK** and **HCLK** to GPIO1 and GPIO0 interfaces that connect to the Arduino IOH and IOL connectors.

APBCLKCFG2SET

This register enables the APB peripheral clocks that connect to the Arduino IOH and IOL connectors, and to components on the V2M-Beetle evaluation board.

APBCLKCFG2CLR

This register disables the APB peripheral clocks that connect to the Arduino IOH and IOL connectors and, to components on the V2M-Beetle evaluation board.

2.12 Board peripherals

The V2M-Beetle evaluation board provides a motion sensor, and temperature sensor, to enable simple demonstration applications without the need for an expansion shield.

The following figure shows the board peripherals, the motion sensor, and the temperature sensor, that connect to the I2C interface, *I2C1*, in the Beetle test chip.

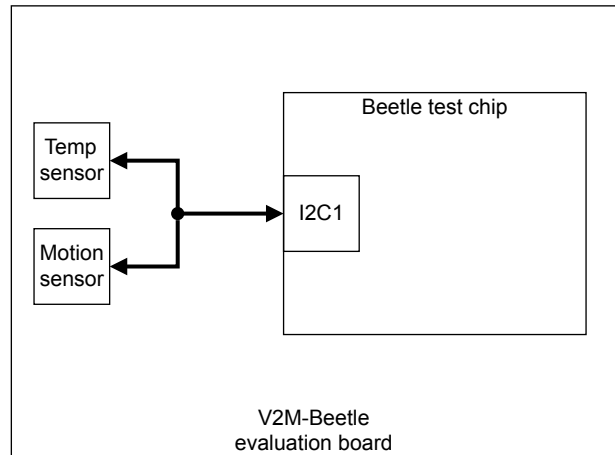


Figure 2-11 V2M-Beetle evaluation board peripherals

Motion sensor

- MMA7660FC 3-axis orientation and motion sensor.
- Slave address: 0x90

Temperature sensor

- TMP102 temperature sensor.
- Slave address: 0x98

Data signals, **SDA** from the motion sensor, and **SDA** from the temperature sensor, connect to **I2C1 Data**, that is, **GPIO1[6]**.

Clock signals, **SCL** from the motion sensor, and **SCL** from the temperature sensor, connect to **I2C1 Clock**, that is, **GPIO1[7]**.

Interrupt signals, **nINT** from the motion sensor, and **nALERT** from the temperature sensor, connect to **I2C1 Interrupt**, that is, **GPIO1[8]**.

2.13 Debug and trace

The V2M-Beetle evaluation board provides debug and trace access to the Beetle test chip.

The following figure shows the V2M-Beetle evaluation board debug and trace system.

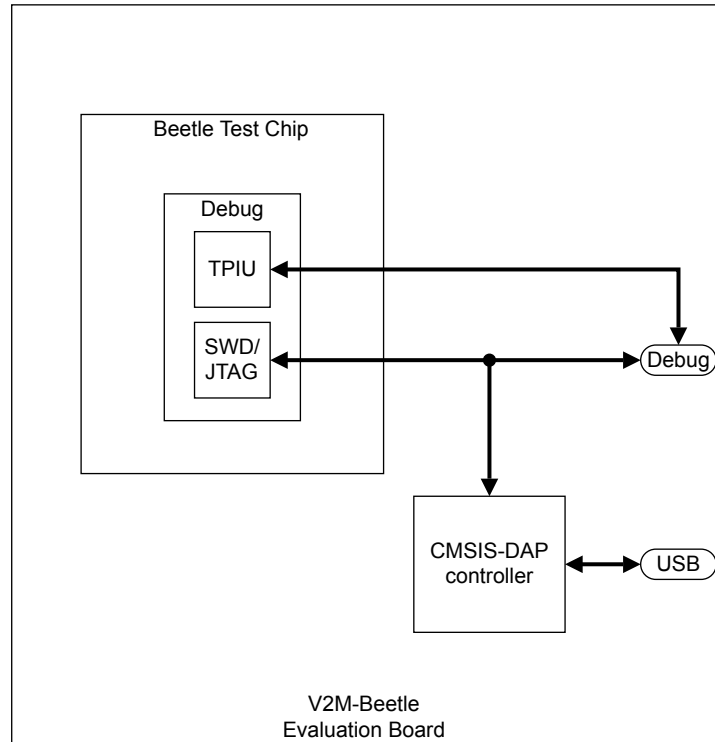


Figure 2-12 V2M-Beetle evaluation board debug and trace system

The V2M-Beetle evaluation board provides:

- SWD debug with external hardware debugger such as ULINK2™.
- 4-bit trace using an external debugger, such as ULINKpro™
- P-JTAG debug.
- CMSIS-DAP debug over USB.

———— **Caution** ————

The external USB 5V supply must be connected for CMSIS-DAP debug over USB. Do not attempt to wake up the CMSIS-DAP controller without the external USB 5V supply being connected because the batteries cannot supply enough current.

Related references

[1.5 Location of components on the V2M-Beetle evaluation board on page 1-16.](#)

[A.1.4 Debug connector on page Appx-A-124.](#)

Chapter 3

Board Configuration and operating modes

This chapter describes board configuration during powerup, loading boot code and test chip programming, CMSIS-DAP programming, and board operating modes.

It contains the following sections:

- [3.1 Board configuration and programming on page 3-42.](#)
- [3.2 Operating modes on page 3-43.](#)

3.1 Board configuration and programming

Configuration of the V2M-Beetle evaluation board proceeds automatically when power is applied to the board.

Overview of V2M-Beetle evaluation board configuration and programming

The following figure shows the configuration system.

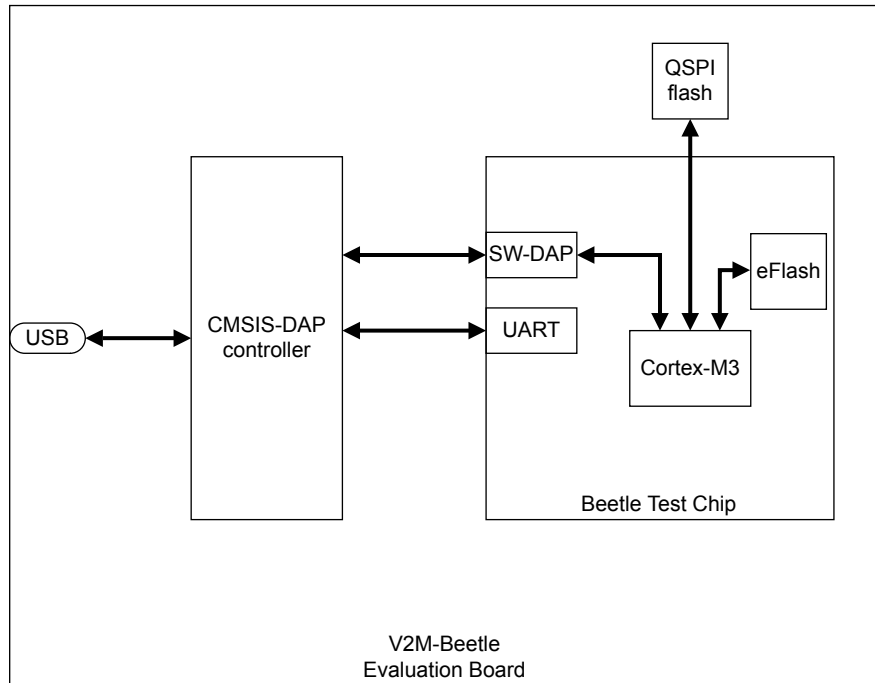


Figure 3-1 V2M-Beetle evaluation board configuration system

The USB port and CMSIS-DAP controller enables drag-and-drop loading of Cortex-M3 boot code and software images. The Cortex-M3-M3 can boot and run code from two possible sources:

- eFlash in the Beetle test chip:
 - eFlash is the default boot option.
- External QSPI flash on the V2M-Beetle evaluation board:
 - The external QSPI flash is the alternative boot option.

3.2 Operating modes

The V2M-Beetle evaluation board has three operating modes.

Board operating modes

The power source that you select for the V2M-Beetle evaluation board defines the operating mode of the board. The operating modes of the V2M-Beetle evaluation board are:

Always on mode

- Operates when the external 5V USB power source is connected.
- The V2M-Beetle evaluation board and Beetle test chip are fully operational.
- Expansion shield support and virtual UART are available.
- The CMSIS-DAP controller is in operational mode. USB debug is available.
- The external 5V USB power source automatically overrides the AAA batteries, if fitted.

Battery Shield mode

This mode is identical to *Always on mode* except for the power source:

- Operates from the 2×AAA batteries (3V).
- The V2M-Beetle evaluation board and Beetle test chip are fully operational.
- Expansion shield support is available.
- The CMSIS-DAP controller is automatically put into *Deep Powerdown* mode. USB debug and USB virtual UART are not available because the external USB 5V power is not connected.

Long Duration mode

- Operates from the 2×AAA batteries (3V).
- The V2M-Beetle evaluation board and Beetle test chip are fully operational.
- Expansion shield support is not available.
- The CMSIS-DAP controller is automatically put into *Deep Powerdown* mode. USB debug and USB virtual UART are not available because the external USB 5V power is not connected.

Note

The external 5V USB power source must not be connected in Battery Shield and Long Duration modes, or it overrides the AAA batteries.

Transitions between V2M-Beetle evaluation board and CMSIS-DAP controller operating modes

Applying power

1. Apply power by either:
 - Fitting 2×AAA batteries:
 - The board powers up in either *Battery Shield* mode or *Long Duration* mode.
 - The CMSIS-DAP automatically goes into *Deep Powerdown* mode to save power:
 - All CMSIS-DAP I/O are set to their default states.
 - CMSIS-DAP internal clocks are turned off except the low- frequency RC clock.
 - USB debug is unavailable.
 - Connecting a USB host cable to the USB port:
 - The board powers up in *Always on* mode.
 - The CMSIS-DAP controller automatically goes into *operational* mode.
 - USB debug is available.

Bringing CMSIS-DAP controller out of *Deep Powerdown* mode

When the board is in *Battery Shield* or *Long Duration* mode, connecting a USB host cable to the USB port:

- Brings the board to *Always on* mode.
- Wakes up the CMSIS-DAP controller, that is, brings it from *Deep Powerdown* mode to *operational* mode.
- Makes USB debug available.

Transition from *Always on* mode to *Battery Shield* or *Long Duration* mode

When the board is in *Always on* mode:

1. Remove the USB host cable. The CMSIS-DAP controller is still operational but USB debug is unavailable.

————— **Caution** —————

- If the batteries are fitted, do not leave the board in this state. Because the USB host cable is absent, USB debug is unavailable. However, the CMSIS-DAP controller remains in *operational* mode and draws battery current which is wasted.

2. Depending on whether batteries are present or not present:
 - If batteries are not present, fit 2×AAA batteries.
 - If batteries are present, remove and then refit the AAA batteries.
3. The board powers up in either *Battery Shield* or *Long Duration* mode.

Powering down the board

1. Briefly press the board *SHUTDOWN* push button.
2. Remove all power from the board, that is, both the 5V USB power source and the 2×AAA batteries.

Chapter 4

Programmers Model

This chapter describes the programmers model of the V2M-Beetle evaluation board.

It contains the following sections:

- *4.1 About this programmers model on page 4-46.*
- *4.2 Memory map on page 4-47.*
- *4.3 Dual timer registers on page 4-51.*
- *4.4 UART registers on page 4-53.*
- *4.5 Watchdog registers on page 4-56.*
- *4.6 GPIO registers on page 4-58.*
- *4.7 System controller registers on page 4-64.*

4.1 About this programmers model

The following information applies to the registers in the test chip.

- Do not attempt to access reserved or unused address locations. Attempting to access these locations can result in UNPREDICTABLE behavior.
- Unless otherwise stated in the accompanying text:
 - Do not modify undefined register bits.
 - Ignore undefined register bits on reads.
 - All register bits are reset to a logic 0 by a system or powerup reset.
 - [4.7.1 System control register summary on page 4-64](#) describes register access type as follows:

RW	Read and write.
RO	Read-only.
WO	Write-only.

4.2 Memory map

The Cortex-M3 in the test chip sees a 32-bit memory map.

The following figure shows the memory map.

0xFFFFFFFF	Default slave	2816MB
0x50000000	Reserved	
0x40020000	Reserved	255MB
0x4001F000	System control registers	4KB
0x40014000	Default slave	44KB
	Reserved	8KB
0x40012000		
0x40011000	GPIO1	4KB
0x40010000	GPIO0	4KB
0x4000F000	True Random Number Generator	4KB
0x4000E000	I2C1	4KB
0x4000D000	SPI1	4KB
0x4000C000	SPI0	4KB
0x4000B000	QuadSPI	4KB
0x4000A000	eFlash control	4KB
0x40009000	eFlash control	4KB
0x40008000	Watchdog	4KB
0x40007000	I2C0	4KB
0x40006000	PL031 RTC	4KB
0x40005000	UART1	4KB
0x40004000	UART0	4KB
0x40003000	eFlash cache	4KB
0x40002000	Dual timer	4KB
0x40001000	Timer 1	4KB
0x40000000	Timer 0	4KB
0x20020000	Default slave	511MB
0x20018000	SRAM3	32KB
0x20010000	SRAM2	32KB
0x20008000	SRAM1	32KB
0x20000000	SRAM0	32KB
0x10040000	Default slave	255MB
0x10000000	QuadSPI	256KB
0x00040000	Default slave	255MB
0x00000000	eFlash/QuadSPI	256KB

**Beetle top-level
application memory map**

Figure 4-1 Beetle test chip memory map

The following table shows the memory map.

Table 4-1 Beetle test chip memory map

Address range	Size	Description: IoT CSS level: test chip level
0x00000000-0x0003FFFF	256KB	eFlash/QuadSPI.
0x00040000-0x0FFFFFFF	255MB	Default slave.
0x10000000-0x1003FFFF	256MB	QuadSPI.
0x10040000-0x1FFFFFFF	255MB	Default slave.
0x20000000-0x20007FFF	32KB	SRAM0.
0x20008000-0x2000FFFF	32KB	SRAM1.
0x20010000-0x20017FFF	32KB	SRAM2.
0x20018000-0x2001FFFF	32KB	SRAM3.
0x20020000-0x3FFFFFFF	511MB	Default slave.
0x40000000-0x40000FFF	4KB	Timer 0.
0x40001000-0x40001FFF	4KB	Timer 1.
0x40002000-0x40002FFF	4KB	Dual timer.
0x40003000-0x40003FFF	4KB	eFlash cache.
0x40004000-0x40004FFF	4KB	UART0.
0x40005000-0x40005FFF	4KB	UART1.
0x40006000-0x40006FFF	4KB	PL031 RTC.
0x40007000-0x40007FFF	4KB	I2C0.
0x40008000-0x40008FFF	4KB	Watchdog.
0x40009000-0x40009FFF	4KB	eFlash controller.
0x4000A000-0x4000AFFF	4KB	eFlash controller.
0x4000B000-0x4000BFFF	4KB	QuadSPI.
0x4000C000-0x4000CFFF	4KB	SPI0.
0x4000D000-0x4000DFFF	4KB	SPI1.
0x4000E000-0x4000EFFF	4KB	I2C1.
0x4000F000-0x4000FFFF	4KB	True Random Number Generator (TRNG).
0x40010000-0x40010FFF	4KB	GPIO0.
0x40011000-0x40011FFF	4KB	GPIO1.
0x40012000-0x40013FFF	8KB	Reserved. Do not write or read from these addresses.
0x40014000-0x4001EFFF	44KB	Default slave.
0x4001F000-0x4001FFFF	4KB	System control registers.
0x40020000-0x4FFFFFFF	255MB	Reserved. Do not write to or read from these addresses.
0x50000000-0xFFFFFFFF	2816MB	Default slave.

The jumper connection on the board controls the remap at 0x00000000:

No jumper	eFlash.
Jumper	QSPI.

Note

When the remap option at 0x00000000 is set to eFlash, QSPI is available at 0x10000000.

See the *ARM® IoT Subsystem for Cortex-M® Technical Reference Manual* for more information on the test chip memory map.

4.3 Dual timer registers

The Beetle test chip contains registers that control the functions of the dual timers. The base memory address of the dual timers control registers is 0x40002000.

Undefined registers are reserved. Software must not attempt to write to or read from these registers.

See the *Dual-input timers* section of the for descriptions of these registers.

The following table shows the dual timer control registers in the test chip in address offset order from the base memory address.

Table 4-2 test chip dual timers control registers summary

Offset	Name	Type	Reset	Width	Function
0x0000	DTIMER1LOAD	RW	0x00000000	32	Dual timer 1 load register.
0x0004	DTIMER1VALUE	RO	0xFFFFFFFF	32	Dual timer 1 current value register.
0x0008	DTIMER1CONTROL	RW	0x00000020	32	Dual timer 1 control register. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x000C	DTIMER1INTCLR	WO	-	32	Dual timer 1 interrupt clear register.
0x0010	DTIMER1RIS	RO	0x00000000	32	Dual timer 1 raw interrupt status register. Bits [31:1] are reserved. Software that reads these bits must ignore these bits.
0x0014	DTIMER1MIS	RO	00000000	32	Dual timer 1 interrupt status register. Bits [31:1] are reserved. Software that reads these bits must ignore these bits.
0x0018	DTIMER1BGLOAD	RW	0x00000000	32	Dual timer 1 background load register.
0x0020	DTIMER2LOAD	RW	0x00000000	32	Dual timer 2 load register.
0x0024	DTIMER2VALUE	RO	0xFFFFFFFF	32	Dual timer 2 current value register.
0x0028	DTIMER2CONTROL	RW	0x00000020	32	Dual timer 2 control register. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x002C	DTIMER2INTCLR	WO	-	32	Dual timer 2 interrupt clear register.
0x0030	DTIMER2RIS	RO	0x00000000	32	Dual timer 2 raw interrupt status register. Bits [31:1] are reserved. Software that reads these bits must ignore these bits.
0x0034	DTIMER2MIS	RO	0x00000000	32	Dual timer 2 interrupt status register. Bits [31:1] are reserved. Software that reads these bits must ignore these bits.
0x0038	DTIMER2BGLOAD	RW	0x00000000	32	Dual timer 2 background load register.
0x0F00	DTIMERITCR	RW	0x00000000	32	Integration test control register.

Table 4-2 test chip dual timers control registers summary (continued)

Offset	Name	Type	Reset	Width	Function
0x0F04	DTIMERITOP	WO	0x00000000	32	Integration test output set register. Bits [31:2] are reserved. Software that writes to this register must write all zeros to these bits.
0x0FD0	DTIMERPERIPHID4	RO	0x00000004	32	Peripheral ID Register 4. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FE0	DTIMERPERIPHID0	RO	0x00000023	32	Peripheral ID Register 0. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FE4	DTIMERPERIPHID1	RO	0x000000B8	32	Peripheral ID Register 1. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FE8	DTIMERPERIPHID2	RO	0x0000000B	32	Peripheral ID Register 2. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FEC	DTIMERPERIPHID3	RO	0x00000000	32	Peripheral ID Register 3. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FF0	DTIMERPCCELLID0	RO	0x0000000D	32	Component ID Register 0. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FF4	DTIMERPCCELLID1	RO	0x000000F0	32	Component ID Register 1. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FF8	DTIMERPCCELLID2	RO	0x00000005	32	Component ID Register 2. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FFC	DTIMERPCCELLID3	RO	0x000000B1	32	Component ID Register 3. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.

4.4 UART registers

The Beetle test chip contains registers that control the functions of the two UARTs, UART0 and UART1. The base memory address of the UART control registers is `0x40004000`.

Undefined registers are reserved. Software must not attempt to write to or read from these registers.

See the *UART* section of the for full descriptions of these registers.

The following table shows the UART control registers in the test chip in address offset order from the base memory address.

Table 4-3 UART control registers summary

Offset	Name	Type	Reset	Width	Function
<code>0x0000</code>	UART0_DATA	RW	-	32	UART0 data value register.
<code>0x0004</code>	UART0_STATE	RW	<code>0x00000000</code>	32	UART0 state register. Bits [31:4] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
<code>0x0008</code>	UART0_CTRL	RW	<code>0x00000000</code>	32	UART0 control register. Bits [31:7] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
<code>0x000C</code>	UART0_INTSTATUS UART0_INTCLEAR	RW	<code>0x00000000</code>	32	UART0 interrupt status and clear register. Bits [31:4] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
<code>0x0010</code>	UART0_BAUDDIV	RW	<code>0x00000000</code>	32	UART0 baud rate divisor register. Bits [31:20] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
<code>0x0FD0</code>	UART0_PID4	RO	<code>0x00000004</code>	32	UART0 peripheral ID Register 4. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
<code>0x0FE0</code>	UART0_PID0	RO	<code>0x00000021</code>	32	UART0 peripheral ID Register 0. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
<code>0x0FE4</code>	UART0_PID1	RO	<code>0x000000B8</code>	32	UART0 peripheral ID Register 1. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
<code>0x0FE8</code>	UART0_PID2	RO	<code>0x0000000B</code>	32	UART0 peripheral ID Register 2. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.

Table 4-3 UART control registers summary (continued)

Offset	Name	Type	Reset	Width	Function
0x0FEC	UART0_PID3	RO	0x00000000	32	UART0 peripheral ID3 register. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FF0	UART0_CID0	RO	0x00000000	32	UART0 component ID0 register. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FF4	UART0_CID1	RO	0x000000F0	32	UART0 component ID1 register. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FF8	UART0_CID2	RO	0x00000005	32	UART0 component ID2 register. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FFC	UART0_CID3	RO	0x000000B1	32	UART0 component ID3 register. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x1000	UART1_DATA	RW	-	32	UART1 data value register.
0x1004	UART1_STATE	RW	0x00000000	32	UART1 state register. Bits [31:4] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1008	UART1_CTRL	RW	0x00000000	32	UART1 control register. Bits [31:7] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x100C	UART1_INTSTATUS UART1_INTCLEAR	RW	0x00000000	32	UART1 interrupt status and clear register. Bits [31:4] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1010	UART1_BAUDDIV	RW	0x00000000	32	UART1 baud rate divisor register. Bits [31:20] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1FD0	UART1_PID4	RO	0x00000004	32	UART1 peripheral ID Register 4. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x1FE0	UART1_PID0	RO	0x00000021	32	UART1 peripheral ID Register 0. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.

Table 4-3 UART control registers summary (continued)

Offset	Name	Type	Reset	Width	Function
0x1FE4	UART1_PID1	RO	0x000000B8	32	UART1 peripheral ID Register 1. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x1FE8	UART1_PID2	RO	0x0000000B	32	UART1 peripheral ID Register 2. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x1FEC	UART1_PID3	RO	0x00000000	32	UART1 peripheral ID Register 3. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x1FF0	UART1_CID0	RO	0x0000000D	32	UART1 component ID Register 0. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x1FF4	UART1_CID1	RO	0x000000F0	32	UART1 component ID Register 1. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x1FF8	UART1_CID2	RO	0x00000005	32	UART1 component ID Register 2. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x1FFC	UART1_CID3	RO	0x000000B1	32	UART1 component ID Register 3. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.

4.5 Watchdog registers

The Beetle test chip contains registers that control the functions of the watchdog module. The base memory address of the watchdog registers is 0x40008000.

Undefined registers are reserved. Software must not attempt to write to or read from these registers.

See the *Watchdog* section of the for descriptions of these registers.

The following table shows the watchdog module control registers in the test chip in address offset order from the base memory address.

Table 4-4 Watchdog control registers summary

Offset	Name	Type	Reset	Width	Function
0x0000	WDOGLOAD	RW	0xFFFFFFFF	32	Watchdog load register.
0x0004	WDOGVALUE	RO	0xFFFFFFFF	32	Current value of watchdog counter register.
0x0008	WDOGCONTROL	RW	0x00000000	8	Timer 1 control register. Bits [31:2] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x000C	WDOGINTCLR	WO	-	32	Watchdog interrupt clear register.
0x0010	WDOGRIS	RO	0x00000000	1	Watchdog interrupt status register. Bits [31:1] are reserved. Software that reads these bits must ignore these bits.
0x0014	WDOGMIS	RO	00000000	1	Watchdog status register. Bits [31:1] are reserved. Software that reads these bits must ignore these bits.
0x0C00	WDOGLOCK	RW	0x00000000	32	Watchdog lock register.
0x0F00	WDOGITCR	RW	0x00000000	32	Watchdog integration test control register. Bits [31:1] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0F04	WDOGITOP	WO	0x00000000	32	Watchdog integration test output set register.
0x0FD0	WDOGPERIPHID4	RO	0x00000004	8	Peripheral ID register 4. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FE0	WDOGPERIPHID0	RO	0x00000024	32	Peripheral ID register 0. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FE4	WDOGPERIPHID1	RO	0x000000B8	1	Peripheral ID register 1. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.

Table 4-4 Watchdog control registers summary (continued)

Offset	Name	Type	Reset	Width	Function
0x0FE8	WDOGPERIPHID2	RO	0x0000000B	1	Peripheral ID register 2. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FEC	WDOGPERIPHID3	RO	0x00000000	32	Peripheral ID register 3. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FF0	WDOGPCCELLID0	RO	0x0000000D	8	Component ID Register 0. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FF4	WDOGCELLID1	RO	0x000000F0	8	Component ID Register 1. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FF8	WDOGPCCELLID2	RO	0x00000005	8	Component ID Register 2. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.
0x0FFC	WDOGPCCELLID3	RO	0x000000B1	8	Component ID Register 3. Bits [31:8] are reserved. Software that reads these bits must ignore these bits.

4.6 GPIO registers

The Beetle test chip contains registers that control the functions of the GPIO pins. The base memory address of the GPIO control registers is `0x40010000`.

Undefined registers are reserved. You must not attempt to write to or read from these registers.

See the *AHB GPIO* section of the *Cortex-M™ System Design Kit Technical Reference Manual* for descriptions of these registers.

————— **Note** —————

Prefixes GPIO0 and GPIO1 are added to the register names to distinguish between the GPIO0 and GPIO1 interfaces on the test chip.

The following table shows the GPIO control registers in the test chip in address offset order from the base memory address.

Table 4-5 GPIO control registers summary

Offset	Name	Type	Reset	Width	Function
0x0000	GPIO0DATA	RW	0x00000000	32	Data value. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0004	GPIO0DATAOUT	RW	0x00000000	32	Data output value. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0010	GPIO0OUTENSET	RW	0x00000000	32	Output enable set. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0014	GPIO0OUTENCLR	RW	0x00000000	32	Output enable clear. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0018	GPIO0ALTFUNCSET	RW	0x00000000	32	Alternative function set. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x001C	GPIO0ALTFUNCCLR	RW	0x00000000	32	Alternative function clear. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.

Table 4-5 GPIO control registers summary (continued)

Offset	Name	Type	Reset	Width	Function
0x0020	GPIO0INTENSET	RW	0x00000000	32	Interrupt enable set. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0024	GPIO0INTENCLR	RW	00000000	32	Interrupt enable clear. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0028	GPIO0INTTYPESET	RW	0x00000000	32	Interrupt type set. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x002C	GPIO0INTTYPECLR	RW	0x00000000	32	Interrupt type clear. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0030	GPIO0INTPOLSET	RW	0x00000000	32	Polarity-level, edge IRQ configuration. Set interrupt polarity bit. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0034	GPIO0INTPOLCLR	RW	0x00000000	32	Polarity-level, edge IRQ configuration. Clear interrupt polarity bit. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0038	GPIO0INTSTATUS INTCLEAR	RW	0x00000000	32	Clear interrupt request. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0FD0	GPIO0PID4	RW	0x00000000	32	Peripheral ID Register 4. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0FE0	GPIO0PID0	RW	0x00000000	32	Peripheral ID Register 0. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.

Table 4-5 GPIO control registers summary (continued)

Offset	Name	Type	Reset	Width	Function
0x0FE4	GPIO0PID1	RW	0x00000000	32	Peripheral ID Register 1. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0FE8	GPIO0PID2	RW	0x00000000	32	Peripheral ID Register 2. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0FEC	GPIO0PID3	RW	0x00000000	32	Peripheral ID Register 3. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0FF0	GPIO0CID0	RW	0x00000000	32	Component ID Register 0. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0FF4	GPIO0CID1	RW	0x00000000	32	Component ID Register 1. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0FF8	GPIO0CID2	RW	0x00000000	32	Component ID Register 2. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x0FFC	GPIO0CID3	RW	0x00000000	32	Component ID Register 3. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1000	GPIO1DATA	RW	0x00000000	32	Data value. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1004	GPIO1DATAOUT	RW	0x00000000	32	Data output value. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.

Table 4-5 GPIO control registers summary (continued)

Offset	Name	Type	Reset	Width	Function
0x1010	GPIO1OUTENSET	RW	0x00000000	32	Output enable set. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1014	GPIO1OUTENCLR	RW	0x00000000	32	Output enable clear. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1018	GPIO1ALTFUNCSET	RW	0x00000000	32	Alternative function set. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x101C	GPIO1ALTFUNCCLR	RW	0x00000000	32	Alternative function clear. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1020	GPIO1INTENSET	RW	0x00000000	32	Interrupt enable set. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1024	GPIO1INTENCLR	RW	0x00000000	32	Interrupt enable clear. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1028	GPIO1INTTYPESET	RW	0x00000000	32	Interrupt type set. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x102C	GPIO1INTTYPECLR	RW	0x00000000	32	Interrupt type clear. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1030	GPIO1INTPOLSET	RW	0x00000000	32	Polarity-level, edge IRQ configuration. Set interrupt polarity bit. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.

Table 4-5 GPIO control registers summary (continued)

Offset	Name	Type	Reset	Width	Function
0x1034	GPIO1INTPOLCLR	RW	0x00000000	32	Polarity-level, edge IRQ configuration. Clear interrupt polarity bit. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1038	GPIO1INTSTATUS INTCLEAR	RW	0x00000000	32	Clear interrupt request. Bits [31:16] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1FD0	GPIO1PID4	RO	0x00000000	32	Peripheral ID Register 4. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1FE0	GPIO1PID0	RO	0x00000000	32	Peripheral ID Register 0. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1FE4	GPIO1PID1	RO	0x00000000	32	Peripheral ID Register 1. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1FE8	GPIO1PID2	RO	0x00000000	32	Peripheral ID Register 2. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1FEC	GPIO1PID3	RO	0x00000000	32	Peripheral ID Register 3. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1FF0	GPIO1CID0	RO	0x00000000	32	Component ID Register 0. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1FF4	GPIO1CID1	RO	0x00000000	32	Component ID Register 1. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.

Table 4-5 GPIO control registers summary (continued)

Offset	Name	Type	Reset	Width	Function
0x1FF8	GPIO1CID2	RO	0x00000000	32	Component ID Register 2. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
0x1FFC	GPIO1CID3	RO	0x00000000	32	Component ID Register 3. Bits [31:8] are reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.

Related concepts

2.3 Beetle test chip GPIO interface on page 2-24.

Related references

Arduino IOL connector on page Appx-A-119.

Arduino IOH connector on page Appx-A-118.

4.7 System controller registers

The test chip contains the system control registers.

This section contains the following subsections:

- [4.7.1 System control register summary](#) on page 4-64.
- [4.7.2 PMUCTRL](#) on page 4-66.
- [4.7.3 RESETOP](#) on page 4-67.
- [4.7.4 RSTINFO](#) on page 4-68.
- [4.7.5 AHBPER0SET](#) on page 4-69.
- [4.7.6 AHBPER0CLR](#) on page 4-70.
- [4.7.7 APBPER0SET](#) on page 4-71.
- [4.7.8 APBPER0CLR](#) on page 4-72.
- [4.7.9 MAINCLK](#) on page 4-74.
- [4.7.10 AUXCLK](#) on page 4-75.
- [4.7.11 AHBCLKCFG0SET](#) on page 4-76.
- [4.7.12 AHBCLKCFG0CLR](#) on page 4-77.
- [4.7.13 AHBCLKCFG1SET](#) on page 4-78.
- [4.7.14 AHBCLKCFG1CLR](#) on page 4-79.
- [4.7.15 AHBCLKCFG2SET](#) on page 4-80.
- [4.7.16 AHBCLKCFG2CLR](#) on page 4-81.
- [4.7.17 APBCLKCFG0SET](#) on page 4-82.
- [4.7.18 APBCLKCFG0CLR](#) on page 4-84.
- [4.7.19 APBCLKCFG1SET](#) on page 4-86.
- [4.7.20 APBCLKCFG1CLR](#) on page 4-88.
- [4.7.21 APBCLKCFG2SET](#) on page 4-90.
- [4.7.22 APBCLKCFG2CLR](#) on page 4-92.
- [4.7.23 AHBPRST0SET](#) on page 4-94.
- [4.7.24 AHBPRST0CLR](#) on page 4-95.
- [4.7.25 APBPRST0SET](#) on page 4-96.
- [4.7.26 APBPRST0CLR](#) on page 4-98.
- [4.7.27 PWRDNCFG0SET](#) on page 4-100.
- [4.7.28 PWRDNCFG0CLR](#) on page 4-101.
- [4.7.29 PWRDNCFG1SET](#) on page 4-102.
- [4.7.30 PWRDNCFG1CLR](#) on page 4-103.
- [4.7.31 RTCRESET](#) on page 4-105.
- [4.7.32 EVENTCFG](#) on page 4-106.
- [4.7.33 PWROVERRIDE0](#) on page 4-106.
- [4.7.34 PWROVERRIDE1](#) on page 4-108.
- [4.7.35 PID4](#) on page 4-110.
- [4.7.36 PID5](#) on page 4-111.
- [4.7.37 PID6](#) on page 4-111.
- [4.7.38 PID7](#) on page 4-112.
- [4.7.39 PID0](#) on page 4-112.
- [4.7.40 PID1](#) on page 4-113.
- [4.7.41 PID2](#) on page 4-113.
- [4.7.42 PID3](#) on page 4-114.
- [4.7.43 CID0](#) on page 4-114.
- [4.7.44 CID1](#) on page 4-115.
- [4.7.45 CID2](#) on page 4-115.
- [4.7.46 CID3](#) on page 4-116.

4.7.1 System control register summary

The base memory address of the system control registers is 0x4001F000.

Undefined registers are reserved. You must not attempt to write to or read from these registers.

See *ARM® IoT Subsystem for Cortex-M® Technical Reference Manual* for information on other registers that control systems in the IoT Compute subsystem, including the eFlash controller and eFlash cache.

The following table shows the system control registers in address offset order from the base memory address.

Table 4-6 V2M-Beetle evaluation board APB system registers summary

Offset	Name	Type	Reset	Width	Description
0x0004	CMSDKPMUCTRL	RO	0x00000001	32	See 4.7.2 PMUCTRL on page 4-66.
0x0008	RESETOP	RW	0x00000000	32	See 4.7.3 RESETOP on page 4-67.
0x0010	RSTINFO	W1C	0x00000000	32	See 4.7.4 RSTINFO on page 4-68.
0x0020	AHBPER0SET	RW	0x00000000	32	See 4.7.5 AHBPER0SET on page 4-69.
0x0024	AHBPER0CLR	RW	0x00000000	32	See 4.7.6 AHBPER0CLR on page 4-70.
0x0030	APBPER0SET	RW	0x00008608	32	See 4.7.7 APBPER0SET on page 4-71.
0x0034	APBPER0CLR	RW	0x00000000	32	See 4.7.8 APBPER0CLR on page 4-72.
0x0040	MAINCLK	RW	0x00000000	32	See 4.7.9 MAINCLK on page 4-74.
0x0044	AUXCLK	RW	0x00000080	32	See 4.7.10 AUXCLK on page 4-75.
0x0048	PLLCTRL	RW	0x00000001	32	See PLLCTRL .
0x004C	PLLSTATUS	RO	0xFFFFFFFF	32	See PLLSTATUS .
0x0080	AHBCLKCFG0SET	RW	0x00000000	32	See 4.7.11 AHBCLKCFG0SET on page 4-76.
0x0084	AHBCLKCFG0CLR	RW	0x00000000	32	See 4.7.12 AHBCLKCFG0CLR on page 4-77.
0x0088	AHBCLKCFG1SET	RW	0x00000000	32	See 4.7.13 AHBCLKCFG1SET on page 4-78.
0x008C	AHBCLKCFG1CLR	RW	0x00000000	32	See 4.7.14 AHBCLKCFG1CLR on page 4-79.
0x0090	AHBCLKCFG2SET	RW	0x00000000	32	See 4.7.15 AHBCLKCFG2SET on page 4-80.
0x0094	AHBCLKCFG2CLR	RW	0x00000000	32	See 4.7.16 AHBCLKCFG2CLR on page 4-81.
0x00A0	APBCLKCFG0SET	RW	0x00000000	32	See 4.7.17 APBCLKCFG0SET on page 4-82.
0x00A4	APBCLKCFG0CLR	RW	0x00000000	32	See 4.7.18 APBCLKCFG0CLR on page 4-84.
0x00A8	APBCLKCFG1SET	RW	0x00000000	32	See 4.7.19 APBCLKCFG1SET on page 4-86.
0x00AC	APBCLKCFG1CLR	RW	0x00000000	32	See 4.7.20 APBCLKCFG1CLR on page 4-88.
0x00B0	APBCLKCFG2SET	RW	0x00000000	32	See 4.7.21 APBCLKCFG2SET on page 4-90.

Table 4-6 V2M-Beetle evaluation board APB system registers summary (continued)

Offset	Name	Type	Reset	Width	Description
0x00B4	APBCLKCFG2CLR	RW	0x00000000	32	See 4.7.22 <i>APBCLKCFG2CLR</i> on page 4-92.
0x00C0	AHBPRST0SET	RW	0x00000000	32	See 4.7.23 <i>AHBPRST0SET</i> on page 4-94.
0x00C4	AHBPRST0CLR	RW	0x00000000	32	See 4.7.24 <i>AHBPRST0CLR</i> on page 4-95.
0x00C8	APBPRST0SET	RW	0x00000600	32	See 4.7.25 <i>APBPRST0SET</i> on page 4-96.
0x00CC	APBPRST0CLR	RW	0x00000000	32	See 4.7.26 <i>APBPRST0CLR</i> on page 4-98.
0x00D0	PWRDNCFG0SET	RW	0x00000000	32	See 4.7.27 <i>PWRDNCFG0SET</i> on page 4-100.
0x00D4	PWRDNCFG0CLR	RW	0x00000000	32	See 4.7.28 <i>PWRDNCFG0CLR</i> on page 4-101.
0x00D8	PWRDNCFG1SET	RW	0x00000000	32	See 4.7.29 <i>PWRDNCFG1SET</i> on page 4-102.
0x00DC	PWRDNCFG1CLR	RW	0x00000000	32	See 4.7.30 <i>PWRDNCFG1CLR</i> on page 4-103.
0x00E0	RTCRESET	WO	0x00000000	32	See 4.7.31 <i>RTCRESET</i> on page 4-105.
0x00E4	EVENTCFG	RW	0x00000000	32	See 4.7.32 <i>EVENTCFG</i> on page 4-106.
0x00F0	PWROVERRIDE0	RW	0x00000000	32	See 4.7.33 <i>PWROVERRIDE0</i> on page 4-106.
0x00F4	PWROVERRIDE1	RW	0x00000000	32	See 4.7.34 <i>PWROVERRIDE1</i> on page 4-108.
0x0FD0	PID4	RO	0x00000004	32	See 4.7.35 <i>PID4</i> on page 4-110.
0x0FE0	PID0	RO	0x00000042	32	See 4.7.39 <i>PID0</i> on page 4-112.
0x0FE4	PID1	RO	0x000000B7	32	See 4.7.40 <i>PID1</i> on page 4-113.
0x0FE8	PID2	RO	0x000000rB	32	See 4.7.41 <i>PID2</i> on page 4-113.
0x0FEC	PID3	RO	0x00000000	32	See 4.7.42 <i>PID3</i> on page 4-114.
0x0FF0	CID0	RO	0x0000000D	32	See 4.7.43 <i>CID0</i> on page 4-114.
0x0FF4	CID1	RO	0x00000010	32	See 4.7.44 <i>CID1</i> on page 4-115.
0x0FF8	CID2	RO	0x00000005	32	See 4.7.45 <i>CID2</i> on page 4-115.
0x0FFC	CID3	RO	0x000000B1	32	See 4.7.46 <i>CID3</i> on page 4-116.

4.7.2 PMUCTRL

The PMUCTRL Register characteristics are:

Purpose

This register is the PMU control register.

Usage constraints

This register is read-only.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

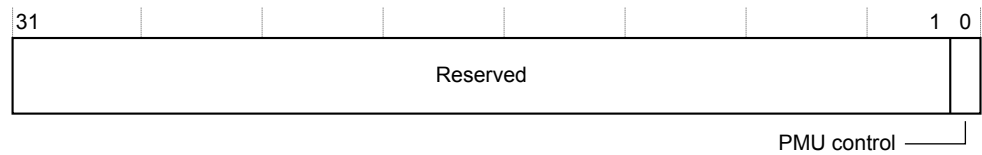


Figure 4-2 PMUCTRL Register bit assignments

The following table shows the bit assignments.

Table 4-7 PMUCTRL Register bit assignments

Bits	Name	Function
[31:1]	-	Reserved. Software that reads this register must ignore these bits.
[0]	PMU control	<p>0b0 PMU not enabled.</p> <p>0b1 PMU enabled.</p>

Note

This bit is always 0b1.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.3 RESETOP

The RESETOP Register characteristics are:

Purpose

Initiates Warm reset if Cortex-M3 locks up.

Usage constraints

Bits [31:1] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

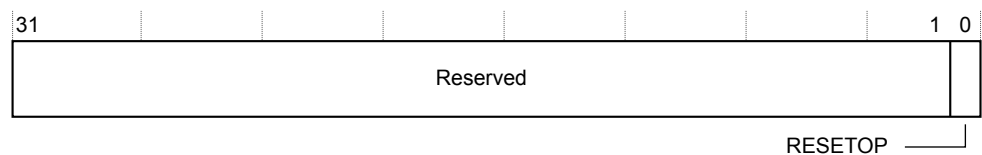


Figure 4-3 RESETOP Register bit assignments

The following table shows the bit assignments.

Table 4-8 RESETOP Register bit assignments

Bits	Name	Function
[31:1]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[0]	RESETOP	0b0 No Warm reset if Cortex-M3 locks up. 0b1 Warm reset if Cortex-M3 locks up.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.4 RSTINFO

The RSTINFO Register characteristics are:

Purpose

Stores the condition that caused the last reset so that application software can act accordingly. This register is writable to enable software to clear it after reading, because the reset process does not clear the register before writing.

Usage constraints

Bits [31:4] are reserved. Bits [3:0] are WIC access, that is, software writes 0b1 to a bit position to clear that bit. Other bits are left unchanged.

Configurations

Available in all V2M-Beetle evaluation board configuration.

The following figure shows the bit assignments.



Figure 4-4 RSTINFO Register bit assignments

The following table shows the bit assignments.

Table 4-9 RSTINFO Register bit assignments

Bits	Name	Function
[31:4]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[3]	M3RSTPWRDNSLP	0b0 No Warm reset if Cortex-M3 is reset from powerdown sleep. 0b1 Warm reset if Cortex-M3 is reset from powerdown sleep.

Table 4-9 RSTINFO Register bit assignments (continued)

Bits	Name	Function
[2]	M3RSTLOCKUP	<p>0b0 No Warm reset if Cortex-M3 is reset from lockup.</p> <p>0b1 Warm reset if Cortex-M3 is reset from lockup.</p>
[1]	M3RSTWDG	<p>0b0 Cortex-M3 Warm reset from watchdog is not enabled.</p> <p>0b1 Cortex-M3 Warm reset from watchdog is enabled.</p>
[0]	M3RSTSYSRESETREQ	<p>0b0 Cortex-M3 Warm reset from SYSRESETREQ is not enabled.</p> <p>0b1 Cortex-M3 Warm reset from SYSRESETREQ is enabled.</p>

Related concepts

4.7.1 System control register summary on page 4-64.

4.7.5 AHBPER0SET

The AHBPER0SET Register characteristics are:

Purpose

Sets AHB peripheral access privilege. This register has the same read value as register AHBPER0CLR.

Usage constraints

Bits [31:2] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

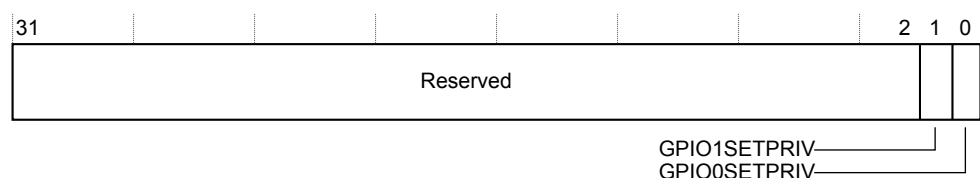


Figure 4-5 AHBPER0SET Register bit assignments

The following table shows the bit assignments.

Table 4-10 AHBPER0SET Register bit assignments

Bits	Name	Function
[31:2]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[1]	GPIO1SETPRIV	0b0 No effect. 0b1 Sets GPIO1 privileged access.
[0]	GPIO0SETPRIV	0b0 No effect. 0b1 Sets GPIO0 privileged access.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.6 AHBPER0CLR

The AHBPER0CLR Register characteristics are:

Purpose

Clears AHB peripheral access privilege. This register has the same read value as register AHBPER0SET.

Usage constraints

Bits [31:2] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

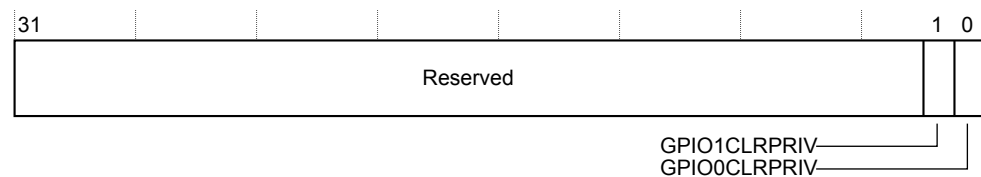


Figure 4-6 AHBPER0CLR Register bit assignments

The following table shows the bit assignments.

Table 4-11 AHBPER0CLR Register bit assignments

Bits	Name	Function
[31:2]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[1]	GPIO1CLRPRIV	0b0 No effect. 0b1 Clears GPIO1 privileged access.
[0]	GPIO0CLRPRIV	0b0 No effect. 0b1 Clears GPIO0 privileged access.

Related concepts

4.7.1 System control register summary on page 4-64.

4.7.7 APBPER0SET

The APBPER0SET Register characteristics are:

Purpose

Sets APB peripheral access privilege. This register has the same read value as register APBPER0CLR.

Usage constraints

Bits [31:16], bits [10:9] and bit [3], are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

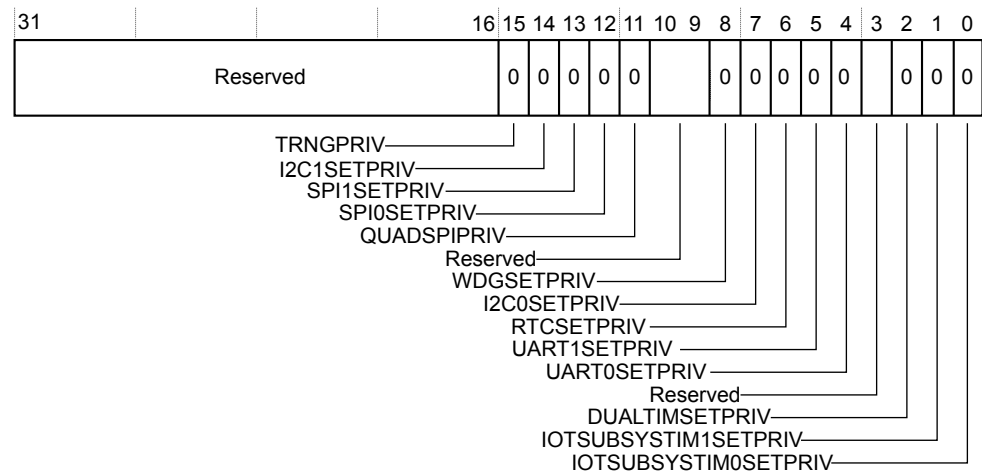


Figure 4-7 APBPER0SET Register bit assignments

The following table shows the bit assignments.

Table 4-12 APBPER0SET Register bit assignments

Bits	Name	Function
[31:16]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[15]	TRNGPRIV	This bit is permanently 0b1. True Random Number Generator has permanent privileged access.
[14]	I2C1SETPRIV	0b0 No effect. 0b1 Sets I2C1 privileged access.
[13]	SPI1SETPRIV	0b0 No effect. 0b1 Sets SPI1 privileged access.
[12]	SPI0SETPRIV	0b0 No effect. 0b1 Sets SPI0 privileged access.

Table 4-12 APBPER0SET Register bit assignments (continued)

Bits	Name	Function
[11]	QUADSPIPRIV	0b0 No effect. 0b1 Sets QuadSPI privileged access.
[10:9]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[8]	WDOGSETPRIV	0b0 No effect. 0b1 Sets watchdog privileged access.
[7]	I2C0SETPRIV	0b0 No effect. 0b1 Sets I2C0 privileged access.
[6]	RTCSETPRIV	0b0 No effect. 0b1 Sets RTC privileged access.
[5]	UART1SETPRIV	0b0 No effect. 0b1 Sets UART1 privileged access.
[4]	UART0SETPRIV	0b0 No effect. 0b1 Sets UART0 privileged access.
[3]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[2]	DUALTIMSETPRIV	0b0 No effect. 0b1 Sets dual-timer privileged access.
[1]	IOTSUBSYSTIM1SETPRIV	0b0 No effect. 0b1 Sets IoT Compute subsystem timer 1 privileged access.
[0]	IOTSUBSYSTIM0SETPRIV	0b0 No effect. 0b1 Sets IoT Compute subsystem timer 0 privileged access.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.8 APBPER0CLR

The APBPER0CLR Register characteristics are:

Purpose

Clears APB peripheral access privilege. This register has the same read value as register APBPER0SET.

Usage constraints

Bits [31:16], bits [10:9] and bit [3], are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

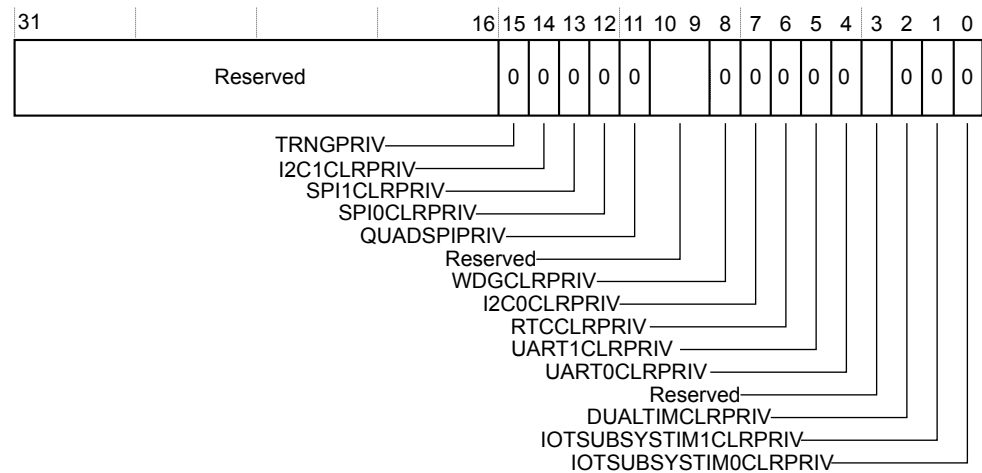


Figure 4-8 APBPER0CLR Register bit assignments

The following table shows the bit assignments.

Table 4-13 APBPER0CLR Register bit assignments

Bits	Name	Function
[31:16]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[15]	TRNGPRIV	This bit is permanently $0b1$. True Random Number Generator has permanent privileged access.
[14]	I2C1CLRPRIV	$0b0$ No effect. $0b1$ Clears I2C1 privileged access.
[13]	SPI1CLRPRIV	$0b0$ No effect. $0b1$ Clears SPI1 privileged access.
[12]	SPI0CLRPRIV	$0b0$ No effect. $0b1$ Clears SPI0 privileged access.
[11]	QUADSPIPRIV	$0b0$ No effect. $0b1$ Clears QuadSPI privileged access.
[10:9]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[8]	WDGCLRPRIV	$0b0$ No effect. $0b1$ Clears watchdog privileged access.
[7]	I2C0CLRPRIV	$0b0$ No effect. $0b1$ Clears I2C0 privileged access.

Table 4-13 APBPER0CLR Register bit assignments (continued)

Bits	Name	Function
[6]	RTCCLRPRIV	0b0 No effect. 0b1 Clears RTC privileged access.
[5]	UART1CLRPRIV	0b0 No effect. 0b1 Clears UART1 privileged access.
[4]	UART0CLRPRIV	0b0 No effect. 0b1 Clears UART0 privileged access.
[3]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[2]	DUALTIMCLRPRIV	0b0 No effect. 0b1 Clears dual-timer privileged access.
[1]	IOTSUBSYSTIM1CLRPRIV	0b0 No effect. 0b1 Clears IoT Compute subsystem timer 1 privileged access.
[0]	IOTSUBSYSTIM0CLRPRIV	0b0 No effect. 0b1 Clears IoT Compute subsystem timer 0 privileged access.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.9 MAINCLK

The MAINCLK Register characteristics are:

Purpose

Configures the main clock control circuitry.

Usage constraints

Bits [31:8] and bits [3:2] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

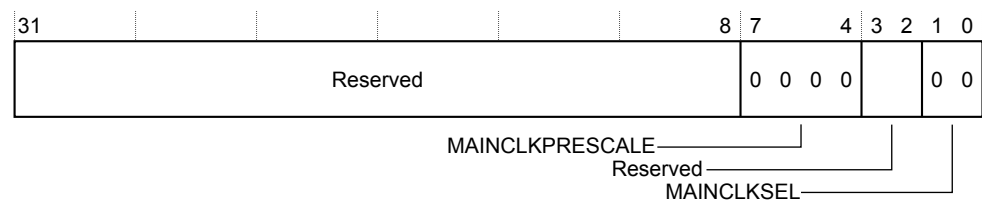


Figure 4-9 MAINCLK Register bit assignments

The following table shows the bit assignments.

Table 4-14 MAINCLK Register bit assignments

Bits	Name	Function
[31:8]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[7:4]	MAINCLKPRESCALE[3:0]	Prescales main clock frequency: 0b0000 Bypass prescaler. No frequency division. 0b0001 - 0b1111 Frequency division factor is (MAINCLKPRESCALE[3:0] + 1).
[3:2]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[1:0]	MAINCLKSEL[1:0]	Selects source for main clock: 0b00 24MHz clock. This is the default input. 0b01 PLL output. 0b10 32kHz. 0b11 Invalid. Do not use.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

[2.4 Clocks on page 2-27.](#)

[Clock PLL.](#)

4.7.10 AUXCLK

The AUXCLK Register characteristics are:

Purpose

Configures the auxiliary clock and RTC clock control circuitry.

Usage constraints

Bits [31:8], bits [6:5], and bits [3:0] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

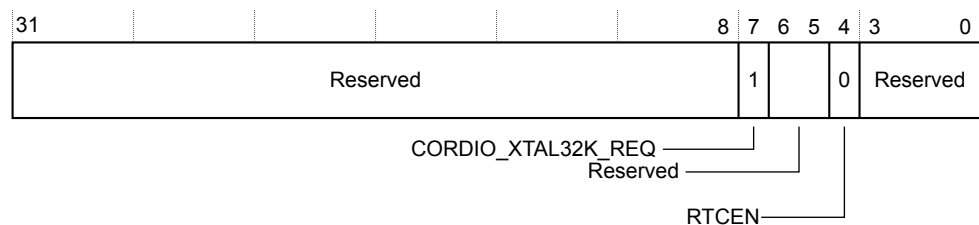


Figure 4-10 AUXCLK Register bit assignments

The following table shows the bit assignments.

Table 4-15 AUXCLK Register bit assignments

Bits	Name	Function				
[31:8]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.				
[7]	CORDIO_XTAL32K_REQ	Request 32kHz crystal frequency from Cordio BT4 radio interface: <table> <tr> <td>0b0</td> <td>No request.</td> </tr> <tr> <td>0b1</td> <td>Request.</td> </tr> </table> <p>The request is enabled by default.</p>	0b0	No request.	0b1	Request.
0b0	No request.					
0b1	Request.					
[6:5]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.				
[4]	RTCEN	RTC clock gate and divider enable: <table> <tr> <td>0b0</td> <td>Not enabled.</td> </tr> <tr> <td>0b1</td> <td>Enabled.</td> </tr> </table>	0b0	Not enabled.	0b1	Enabled.
0b0	Not enabled.					
0b1	Enabled.					
[3:0]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.				

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.11 AHBCLKCFG0SET

The AHBCLKCFG0SET Register characteristics are:

Purpose

Enables AHB peripheral clocks. This register operates when the test chip is in the Active state. This register has the same read value as the AHBCLKCFG0CLR register.

Usage constraints

Bits [31:2] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

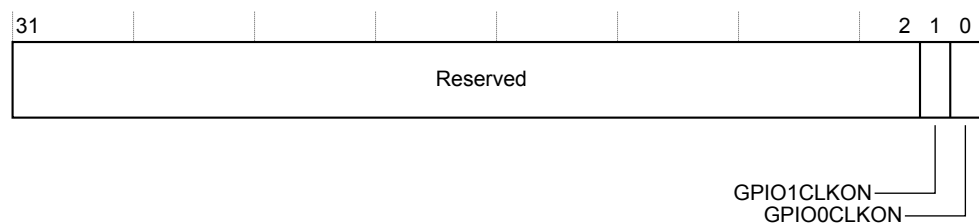


Figure 4-11 AHBCLKCFG0SET Register bit assignments

The following table shows the bit assignments.

Table 4-16 AHBCLKCFG0SET Register bit assignments

Bits	Name	Function
[31:2]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[1]	GPIO1CLKON	Enables GPIO1 AHB peripheral clocks: 0b0 No effect. 0b1 FCLK and HCLK both on.
[0]	GPIO0CLKON	Enables GPIO0 AHB peripheral clocks: 0b0 No effect. 0b1 FCLK and HCLK both on.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.12 AHBCLKCFG0CLR

The AHBCLKCFG0CLR Register characteristics are:

Purpose

Disables AHB peripheral clocks. This register operates when the test chip is in the Active state. This register has the same read value as the AHBCLKCFG1SET register.

Usage constraints

Bits [31:2] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

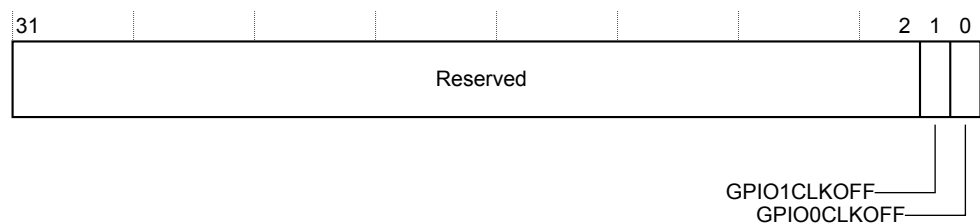


Figure 4-12 AHBCLKCFG0CLR Register bit assignments

The following table shows the bit assignments.

Table 4-17 AHBCLKCFG0CLR Register bit assignments

Bits	Name	Function
[31:2]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[1]	GPIO1CLKOFF	Disables GPIO1 AHB peripheral clocks: 0b0 No effect. 0b1 FCLK and HCLK both off.
[0]	GPIO0CLKOFF	Disables GPIO0 AHB peripheral clocks: 0b0 No effect. 0b1 FCLK and HCLK both off.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.13 AHBCLKCFG1SET

The AHBCLKCFG1SET Register characteristics are:

Purpose

Enables AHB peripheral clocks. This register operates when the test chip is in the Sleep state. This register has the same read value as the AHBCLKCFG1CLR register.

Usage constraints

Bits [31:2] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

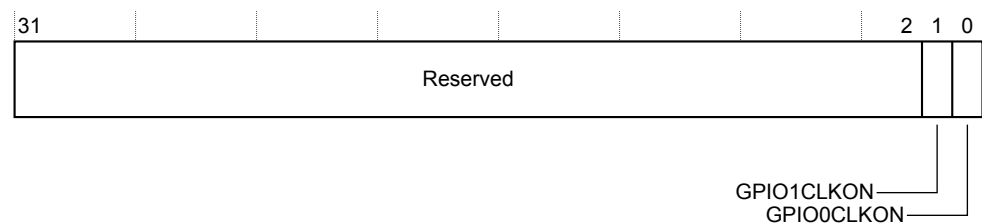


Figure 4-13 AHBCLKCFG1SET Register bit assignments

The following table shows the bit assignments.

Table 4-18 AHBCLKCFG1SET Register bit assignments

Bits	Name	Function
[31:2]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[1]	GPIO1CLKON	Enables GPIO1 AHB peripheral clocks: 0b0 No effect. 0b1 FCLK and HCLK both on.
[0]	GPIO0CLKON	Enables GPIO0 AHB peripheral clocks: 0b0 No effect. 0b1 FCLK and HCLK both on.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.14 AHBCLKCFG1CLR

The AHBCLKCFG1CLR Register characteristics are:

Purpose

Disables AHB peripheral clocks. This register operates when the test chip is in the Sleep state. This register has the same read value as the AHBCLKCFG1SET register.

Usage constraints

Bits [31:2] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

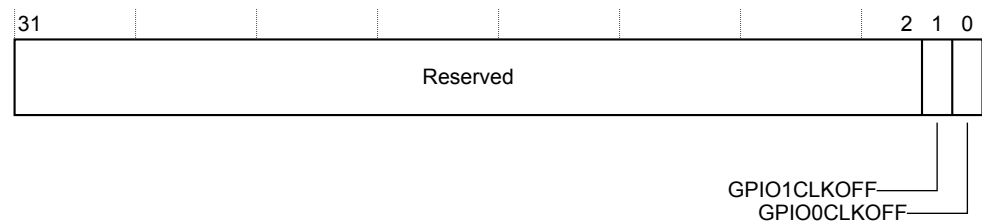


Figure 4-14 AHBCLKCFG1CLR Register bit assignments

The following table shows the bit assignments.

Table 4-19 AHBCLKCFG1CLR Register bit assignments

Bits	Name	Function
[31:2]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[1]	GPIO1CLKOFF	Disables GPIO1 AHB peripheral clocks: 0b0 No effect. 0b1 FCLK and HCLK both off.
[0]	GPIO0CLKOFF	Disables GPIO0 AHB peripheral clocks: 0b0 No effect. 0b1 FCLK and HCLK both off.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.15 AHBCLKCFG2SET

The AHBCLKCFG2SET Register characteristics are:

Purpose

Enables AHB peripheral clocks. This register operates when the test chip is in the deep sleep state, or the powerdown state. This register has the same read value as the AHBCLKCFG2CLR register.

Usage constraints

Bits [31:2] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

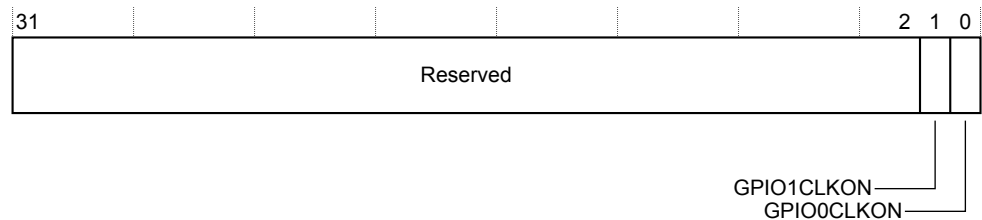


Figure 4-15 AHBCLKCFG2SET Register bit assignments

The following table shows the bit assignments.

Table 4-20 AHBCLKCFG2SET Register bit assignments

Bits	Name	Function
[31:2]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[1]	GPIO1CLKON	Enables GPIO1 AHB peripheral clocks: 0b0 No effect. 0b1 FCLK and HCLK both on.
[0]	GPIO0CLKON	Enables GPIO0 AHB peripheral clocks: 0b0 No effect. 0b1 FCLK and HCLK both on.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.16 AHBCLKCFG2CLR

The AHBCLKCFG2CLR Register characteristics are:

Purpose

Disables AHB peripheral clocks. This register operates when the test chip is in the deep sleep state, or the powerdown state. This register has the same read value as the AHBCLKCFG2SET register.

Usage constraints

Bits [31:2] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

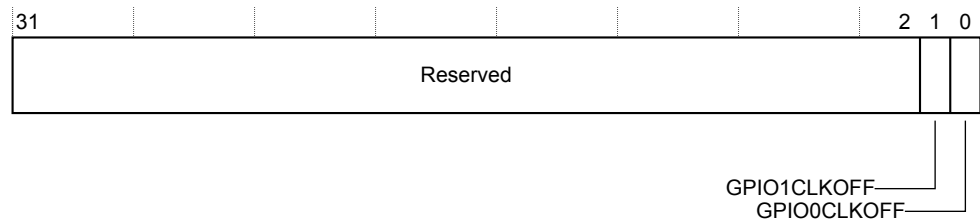


Figure 4-16 AHBCLKCFG2CLR Register bit assignments

The following table shows the bit assignments.

Table 4-21 AHBCLKCFG2CLR Register bit assignments

Bits	Name	Function
[31:2]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[1]	GPIO1CLKOFF	Disables GPIO1 AHB peripheral clocks: 0b0 No effect. 0b1 FCLK and HCLK both off.
[0]	GPIO0CLKOFF	Disables GPIO0 AHB peripheral clocks: 0b0 No effect. 0b1 FCLK and HCLK both off.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.17 APBCLKCFG0SET

The APBCLKCFG0SET Register characteristics are:

Purpose

Enables APB peripheral clocks. This register operates when the test chip is in the Active state. This register has the same read value as the APBCLKCFG0CLR register.

Usage constraints

Bits [31:16], bits [10:9], bit [6], and bit [3] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

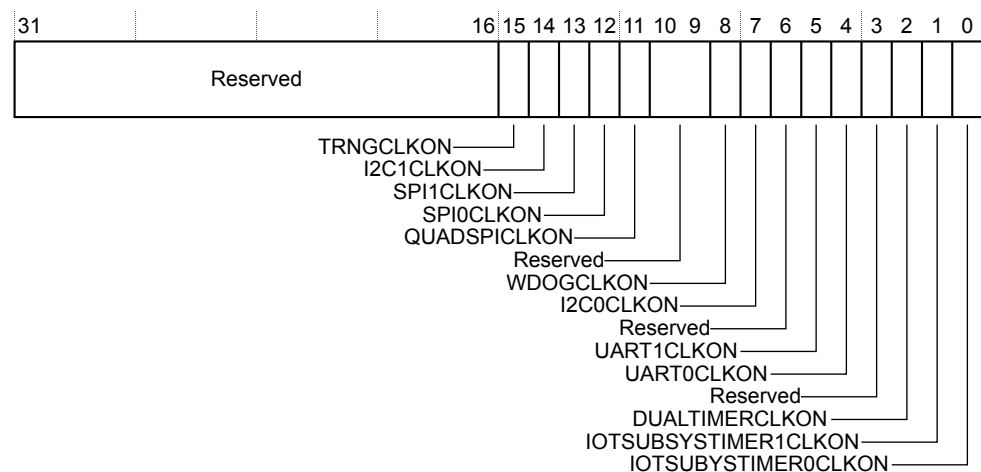


Figure 4-17 APBCLKCFG0SET Register bit assignments

The following table shows the bit assignments.

Table 4-22 APBCLKCFG0SET Register bit assignments

Bits	Name	Function
[31:16]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[15]	TRNGCLKON	Enables True Random Number Generator (TRNG) clock: 0b0 No effect. 0b1 TRNG clock on.
[14]	I2C1CLKON	Enables I2C1 clock: 0b0 No effect. 0b1 I2C1 clock on.
[13]	SPI1CLKON	Enables SPI1 clock: 0b0 No effect. 0b1 SPI1 clock on.
[12]	SPI0CLKON	Enables SPI0 clock: 0b0 No effect. 0b1 SPI0 clock on.
[11]	QUADSPICLKON	Enables QUADSPI clock: 0b0 No effect. 0b1 QUADSPI clock on.
[10:9]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[8]	WDGCLKON	Enables Watchdog clock: 0b0 No effect. 0b1 Watchdog clock on.
[7]	I2C0CLKON	Enables I2C0 clock: 0b0 No effect. 0b1 I2C0 clock on.
[6]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[5]	UART1CLKON	Enables UART1 clock: 0b0 No effect. 0b1 UART1 clock on.
[4]	UART0CLKON	Enables UART0 clock: 0b0 No effect. 0b1 UART0 clock on.

Table 4-22 APBCLKCFG0SET Register bit assignments (continued)

Bits	Name	Function
[3]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[2]	DUALTIMERCLKON	Enables dual-timer clock: 0b0 No effect. 0b1 Dual-timer clock on.
[1]	IOTSUBSYSTEMTIMER1CLKON	Enables IoT Compute subsystem timer 1 clock: 0b0 No effect. 0b1 IoT Compute subsystem timer 1 clock on.
[0]	IOTSUBSYSTEMTIMER0CLKON	Enables IoT Compute subsystem timer 0 clock: 0b0 No effect. 0b1 IoT Compute subsystem timer 0 clock on.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.18 APBCLKCFG0CLR

The APBCLKCFG0CLR Register characteristics are:

Purpose

Disables APB peripheral clocks. This register operates when the test chip is in the Active state. This register has the same read value as the APBCLKCFG0SET register.

Usage constraints

Bits [31:16], bits [10:9], bit [6], and bit [3] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

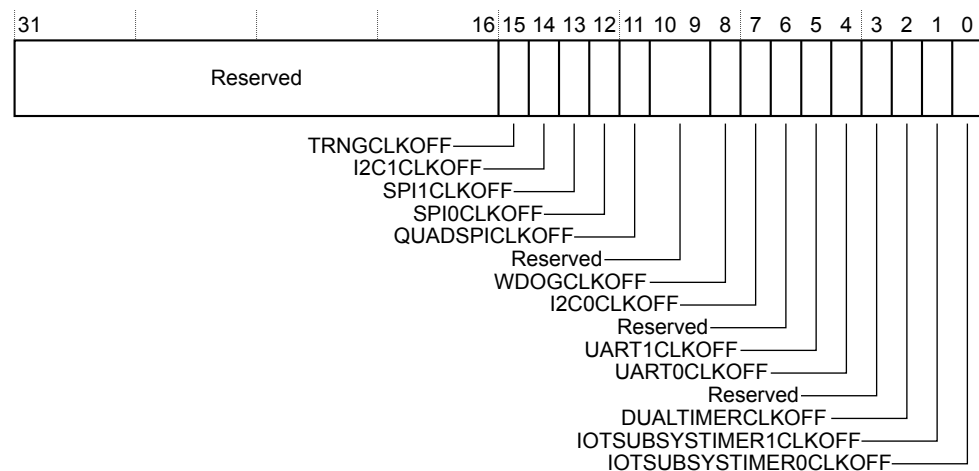


Figure 4-18 APBCLKCFG0CLR Register bit assignments

The following table shows the bit assignments.

Table 4-23 APBCLKCFG0CLR Register bit assignments

Bits	Name	Function
[31:16]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[15]	TRNGCLKOFF	Disables True Random Number Generator (TRNG) clock: 0b0 No effect. 0b1 TRNG clock off.
[14]	I2C1CLKOFF	Disables I2C1 clock: 0b0 No effect. 0b1 I2C1 clock off.
[13]	SPI1CLKOFF	Disables SPI1 clock: 0b0 No effect. 0b1 SPI1 clock off.
[12]	SPI0CLKOFF	Disables SPI0 clock: 0b0 No effect. 0b1 SPI0 clock off.
[11]	QUADSPICCLKOFF	Disables QUADSPI clock: 0b0 No effect. 0b1 QUADSPI clock off.
[10:9]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[8]	WDOGCLKOFF	Disables Watchdog clock: 0b0 No effect. 0b1 Watchdog clock off.
[7]	I2C0CLKOFF	Disables I2C0 clock: 0b0 No effect. 0b1 I2C0 clock off.
[6]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[5]	UART1CLKOFF	Disables UART1 clock: 0b0 No effect. 0b1 UART1 clock off.
[4]	UART0CLKOFF	Disables UART0 clock: 0b0 No effect. 0b1 UART0 clock off.

Table 4-23 APBCLKCFG0CLR Register bit assignments (continued)

Bits	Name	Function
[3]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[2]	DUALTIMERCLKOFF	Disables dual-timer clock: 0b0 No effect. 0b1 Dual-timer clock off.
[1]	IOTSUBSYSTIMER1CLKOFF	Disables IoT Compute subsystem timer 1 clock: 0b0 No effect. 0b1 IoT Compute subsystem timer 1 clock off.
[0]	IOTSUBSYSTIMER0CLKOFF	Disables IoT Compute subsystem timer 0 clock: 0b0 No effect. 0b1 IoT Compute subsystem timer 0 clock off.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.19 APBCLKCFG1SET

The APBCLKCFG1SET Register characteristics are:

Purpose

Enables APB peripheral clocks. This register operates when the test chip is in the Sleep state. This register has the same read value as the APBCLKCFG1CLR register.

Usage constraints

Bits [31:16], bits [10:9], bit [6], and bit [3] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

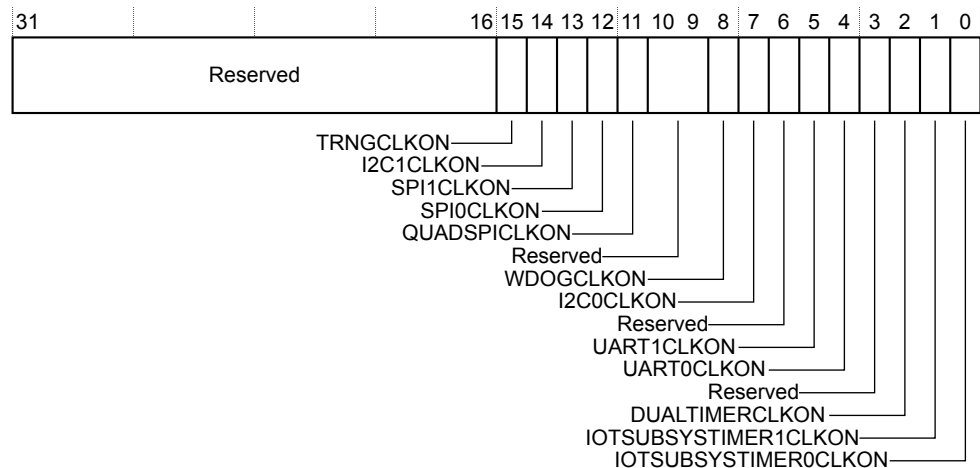


Figure 4-19 APBCLKCFG1SET Register bit assignments

The following table shows the bit assignments.

Table 4-24 APBCLKCFG1SET Register bit assignments

Bits	Name	Function
[31:16]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[15]	TRNGCLKON	Enables True Random Number Generator (TRNG) clock: 0b0 No effect. 0b1 TRNG clock on.
[14]	I2C1CLKON	Enables I2C1 clock: 0b0 No effect. 0b1 I2C1 clock on.
[13]	SPI1CLKON	Enables SPI1 clock: 0b0 No effect. 0b1 SPI1 clock on.
[12]	SPI0CLKON	Enables SPI0 clock: 0b0 No effect. 0b1 SPI0 clock on.
[11]	QUADSPICLKON	Enables QUADSPI clock: 0b0 No effect. 0b1 QUADSPI clock on.
[10:9]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[8]	WDGCLKON	Enables Watchdog clock: 0b0 No effect. 0b1 Watchdog clock on.
[7]	I2C0CLKON	Enables I2C0 clock: 0b0 No effect. 0b1 I2C0 clock on.
[6]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[5]	UART1CLKON	Enables UART1 clock: 0b0 No effect. 0b1 UART1 clock on.
[4]	UART0CLKON	Enables UART0 clock: 0b0 No effect. 0b1 UART0 clock on.

Table 4-24 APBCLKCFG1SET Register bit assignments (continued)

Bits	Name	Function
[3]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[2]	DUALTIMERCLKON	Enables dual-timer clock: 0b0 No effect. 0b1 Dual-timer clock on.
[1]	IOTSUBSYSTEMTIMER1CLKON	Enables IoT Compute subsystem timer 1 clock: 0b0 No effect. 0b1 IoT Compute subsystem timer 1 clock on.
[0]	IOTSUBSYSTEMTIMER0CLKON	Enables IoT Compute subsystem timer 0 clock on: 0b0 No effect. 0b1 IoT Compute subsystem timer 0 clock on.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.20 APBCLKCFG1CLR

The APBCLKCFG1CLR Register characteristics are:

Purpose

Disables APB peripheral clocks. This register operates when the test chip is in the Sleep state. This register has the same read value as the APBCLKCFG1SET register.

Usage constraints

Bits [31:16], bits [10:9], bit [6], and bit [3] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

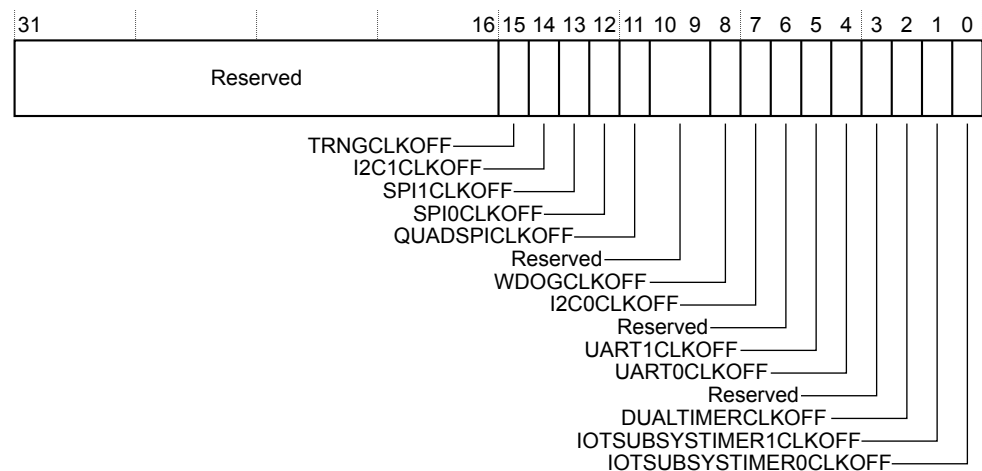


Figure 4-20 APBCLKCFG1CLR Register bit assignments

The following table shows the bit assignments.

Table 4-25 APBCLKCFG1CLR Register bit assignments

Bits	Name	Function
[31:16]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[15]	TRNGCLKOFF	Disables True Random Number Generator (TRNG) clock: 0b0 No effect. 0b1 TRNG clock off.
[14]	I2C1CLKOFF	Disables I2C1 clock: 0b0 No effect. 0b1 I2C1 clock off.
[13]	SPI1CLKOFF	Disables SPI1 clock: 0b0 No effect. 0b1 SPI1 clock off.
[12]	SPI0CLKOFF	Disables SPI0 clock: 0b0 No effect. 0b1 SPI0 clock off.
[11]	QUADSPICCLKOFF	Disables QUADSPI clock: 0b0 No effect. 0b1 QUADSPI clock off.
[10:9]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[8]	WDOGCLKOFF	Disables Watchdog clock: 0b0 No effect. 0b1 Watchdog clock off.
[7]	I2C0CLKOFF	Disables I2C0 clock off: 0b0 No effect. 0b1 I2C0 clock off.
[6]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[5]	UART1CLKOFF	Disables UART1 clock: 0b0 No effect. 0b1 UART1 clock off.
[4]	UART0CLKOFF	Disables UART0 clock: 0b0 No effect. 0b1 UART0 clock off.

Table 4-25 APBCLKCFG1CLR Register bit assignments (continued)

Bits	Name	Function
[3]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[2]	DUALTIMERCLKOFF	Disables dual-timer clock: 0b0 No effect. 0b1 Dual-timer clock off.
[1]	IOTSUBSYSTEMTIMER1CLKOFF	Disables IoT Compute subsystem timer 1 clock: 0b0 No effect. 0b1 IoT Compute subsystem timer 1 clock off.
[0]	IOTSUBSYSTEMTIMER0CLKOFF	Disables IoT Compute subsystem timer 0 clock: 0b0 No effect. 0b1 IoT Compute subsystem timer 0 clock off.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.21 APBCLKCFG2SET

The APBCLKCFG2SET Register characteristics are:

Purpose

Enables APB peripheral clocks. This register operates when the test chip is in the deep sleep state, or the powerdown state. This register has the same read value as the APBCLKCFG2CLR register.

Usage constraints

Bits [31:16], bits [10:9], bit [6], and bit [3] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

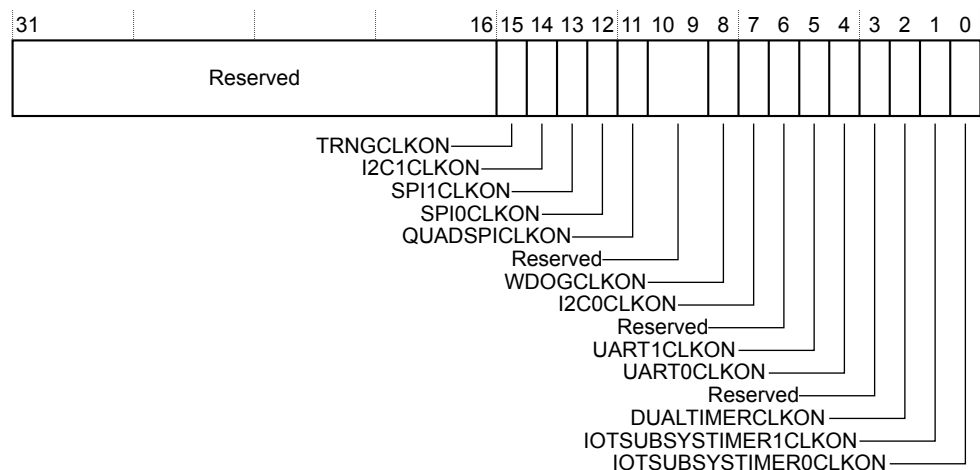


Figure 4-21 APBCLKCFG2SET Register bit assignments

The following table shows the bit assignments.

Table 4-26 APBCLKCFG2SET Register bit assignments

Bits	Name	Function
[31:16]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[15]	TRNGCLKON	Enables True Random Number Generator (TRNG) clock: 0b0 No effect. 0b1 TRNG clock on.
[14]	I2C1CLKON	Enables I2C1 clock: 0b0 No effect. 0b1 I2C1 clock on.
[13]	SPI1CLKON	Enables SPI1 clock: 0b0 No effect. 0b1 SPI1 clock on.
[12]	SPI0CLKON	Enables SPI0 clock: 0b0 No effect. 0b1 SPI0 clock on.
[11]	QUADSPICLKON	Enables QUADSPI clock: 0b0 No effect. 0b1 QUADSPI clock on.
[10:9]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[8]	WDOGCLKON	Enables Watchdog clock: 0b0 No effect. 0b1 Watchdog clock on.
[7]	I2C0CLKON	Enables I2C0 clock: 0b0 No effect. 0b1 I2C0 clock on.
[6]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[5]	UART1CLKON	Enables UART1 clock: 0b0 No effect. 0b1 UART1 clock on.

Table 4-26 APBCLKCFG2SET Register bit assignments (continued)

Bits	Name	Function
[4]	UART0CLKON	Enables UART0 clock: 0b0 No effect. 0b1 UART0 clock on.
[3]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[2]	DUALTIMERCLKON	Enables dual-timer clock: 0b0 No effect. 0b1 Dual-timer clock on.
[1]	IOTSUBSYSTIMER1CLKON	Enables IoT Compute subsystem timer 1 clock: 0b0 No effect. 0b1 IoT Compute subsystem timer 1 clock on.
[0]	IOTSUBSYSTIMER0CLKON	Enables IoT Compute subsystem timer 0 clock: 0b0 No effect. 0b1 IoT Compute subsystem timer 0 clock on.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.22 APBCLKCFG2CLR

The APBCLKCFG2CLR Register characteristics are:

Purpose

Disables APB peripheral clocks. This register operates when the test chip is in the deep sleep state, or the powerdown state. This register has the same read value as the APBCLKCFG2CLR register.

Usage constraints

Bits [31:16], bits [10:9], bit [6], and bit [3] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

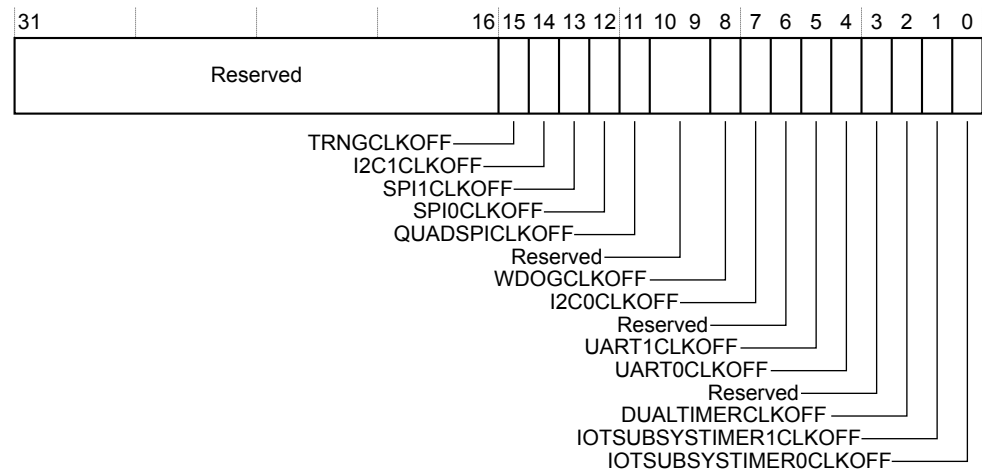


Figure 4-22 APBCLKCFG2CLR Register bit assignments

The following table shows the bit assignments.

Table 4-27 APBCLKCFG2CLR Register bit assignments

Bits	Name	Function
[31:16]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[15]	TRNGCLKOFF	Disables True Random Number Generator (TRNG) clock: 0b0 No effect. 0b1 TRNG clock off.
[14]	I2C1CLKOFF	Disables I2C1 clock: 0b0 No effect. 0b1 I2C1 clock off.
[13]	SPI1CLKOFF	Disables SPI1 clock: 0b0 No effect. 0b1 SPI1 clock off.
[12]	SPI0CLKOFF	Disables SPI0 clock: 0b0 No effect. 0b1 SPI0 clock off.
[11]	QUADSPICLKOFF	Disables QUADSPI clock: 0b0 No effect. 0b1 QUADSPI clock off.
[10:9]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.

Table 4-27 APBCLKCFG2CLR Register bit assignments (continued)

Bits	Name	Function
[8]	WDOGCLKOFF	Disables Watchdog clock: 0b0 No effect. 0b1 Watchdog clock off.
[7]	I2C0CLKOFF	Disables I2C0 clock: 0b0 No effect. 0b1 I2C0 clock off.
[6]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[5]	UART1CLKOFF	Disables UART1 clock: 0b0 No effect. 0b1 UART1 clock off.
[4]	UART0CLKOFF	Disables UART0 clock: 0b0 No effect. 0b1 UART0 clock off.
[3]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[2]	DUALTIMERCLKOFF	Disables dual-timer clock: 0b0 No effect. 0b1 Dual-timer clock off.
[1]	IOTSUBSYSTEMTIMER1CLKOFF	Disables IoT Compute subsystem timer 1 clock: 0b0 No effect. 0b1 IoT Compute subsystem timer 1 clock off.
[0]	IOTSUBSYSTEMTIMER0CLKOFF	Disables IoT Compute subsystem timer 0 clock: 0b0 No effect. 0b1 IoT Compute subsystem timer 0 clock off.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.23 AHBPRST0SET

The AHBPRST0SET Register characteristics are:

Purpose

Enables **nPOR** as the reset signal for the AHB peripherals. When set, the system-wide software reset does not reset the peripheral which is necessary if the peripheral needs to wake the system. This register has the same read value as the AHBPRST0CLR register.

Usage constraints

Bits [31:4] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

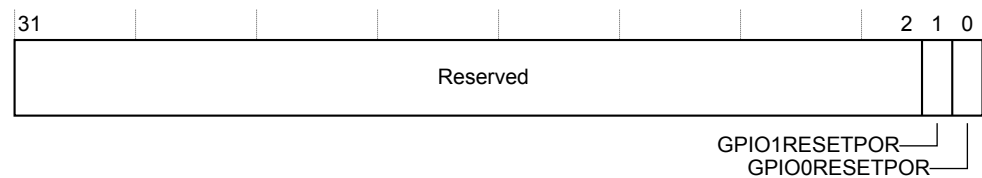


Figure 4-23 AHBPRST0SET Register bit assignments

The following table shows the bit assignments.

Table 4-28 AHBPRST0SET Register bit assignments

Bits	Name	Function
[31:2]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[1]	GPIO1RESETPOR	<p>0b0 No effect.</p> <p>0b1 Enables nPOR as the reset signal for the GPIO1 AHB peripherals.</p>
[0]	GPIO0RESETPOR	<p>0b0 No effect.</p> <p>0b1 Enables nPOR as the reset signal for the GPIO0 AHB peripherals.</p>

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.24 AHBPRST0CLR

The AHBPRST0CLR Register characteristics are:

Purpose

Disables **nPOR** as the reset signal for the AHB peripherals. This register has the same read value as the AHBPRST0SET register.

Usage constraints

Bits [31:4] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

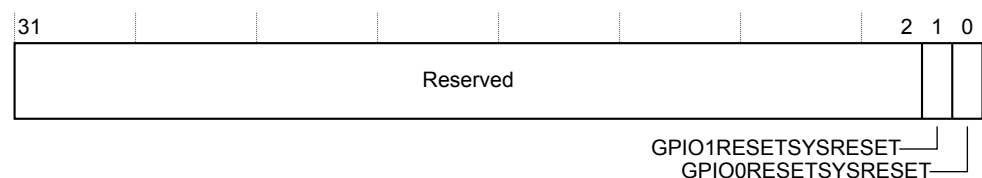


Figure 4-24 AHBPRST0CLR Register bit assignments

The following table shows the bit assignments.

Table 4-29 AHBPRST0CLR Register bit assignments

Bits	Name	Function
[31:2]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[1]	GPIO1RESETPOR	0b0 No effect. 0b1 Selects system reset as the reset signal for the GPIO1 AHB peripherals.
[0]	GPIO0RESETPOR	0b0 No effect. 0b1 Selects system reset as the reset signal for the GPIO0 AHB peripherals.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.25 APBPRST0SET

The APBPRST0SET Register characteristics are:

Purpose

Enables **nPOR** as the reset signal for the APB peripherals. When set, the system-wide software reset does not reset the peripheral which is necessary if the peripheral needs to wake the system. This register has the same read value as the APBPRST0CLR register.

Usage constraints

Bits [31:15], bits [10:8], and bit [3] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

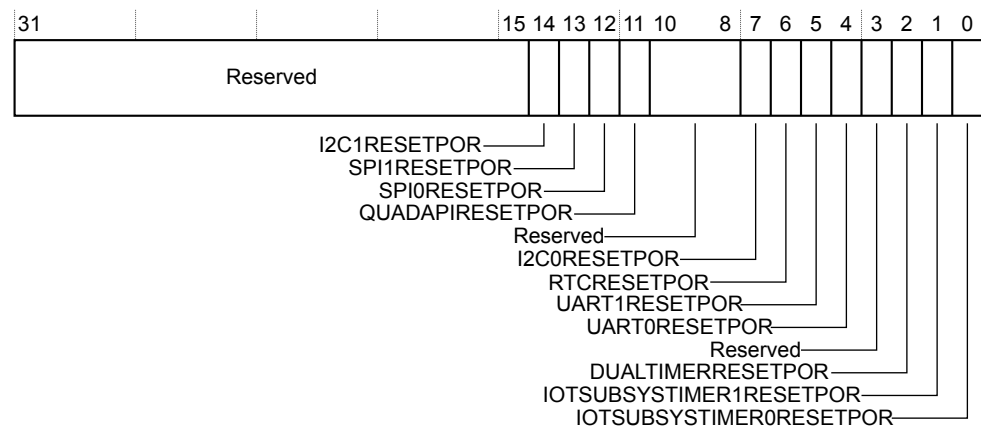


Figure 4-25 APBPRST0SET Register bit assignments

The following table shows the bit assignments.

Table 4-30 APBPRST0SET Register bit assignments

Bits	Name	Function
[31:15]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[14]	I2C1RESETPOR	<p>0b0 No effect.</p> <p>0b1 Selects nPOR as the reset signal for the I2C1 peripheral.</p>
[13]	SPI1RESETPOR	<p>0b0 No effect.</p> <p>0b1 Selects nPOR as the reset signal for the SPI1 peripheral.</p>
[12]	SPI0RESETPOR	<p>0b0 No effect.</p> <p>0b1 Selects nPOR as the reset signal for the SPI0 peripheral.</p>
[11]	QUADSPICRESETPOR	<p>0b0 No effect.</p> <p>0b1 Selects nPOR as the reset signal for the QUADSPI.</p>
[10:8]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[7]	I2C0RESETPOR	<p>0b0 No effect.</p> <p>0b1 Selects nPOR as the reset signal for the I2C0 peripheral.</p>
[6]	RTCRESETPOR	<p>0b0 No effect.</p> <p>0b1 Selects nPOR as the reset signal for the real-time clock.</p>
[5]	UART1RESETPOR	<p>0b0 No effect.</p> <p>0b1 Selects nPOR as the reset signal for UART1.</p>
[4]	UART0RESETPOR	<p>0b0 No effect.</p> <p>0b1 Selects nPOR as the reset signal for UART0.</p>
[3]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[2]	DUALTIMERRESETPOR	<p>0b0 No effect.</p> <p>0b1 Selects nPOR as the reset signal for the dual-timer.</p>

Table 4-30 APBPRST0SET Register bit assignments (continued)

Bits	Name	Function
[1]	IOTSUBSYSTIMER1RESETPOR	<p>0b0 No effect.</p> <p>0b1 Selects nPOR as the reset signal for the IoT Compute subsystem timer 1.</p>
[0]	IOTSUBSYSTIMER0RESETPOR	<p>0b0 No effect.</p> <p>0b1 Selects nPOR as the reset signal for the IoT Compute subsystem timer 0.</p>

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.26 APBPRST0CLR

The APBPRST0CLR Register characteristics are:

Purpose

Disables **nPOR** as the reset signal for the APB peripherals. This register has the same read value as the APBPRST0SET register.

Usage constraints

Bits [31:15], bits [10:8], and bit [3] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

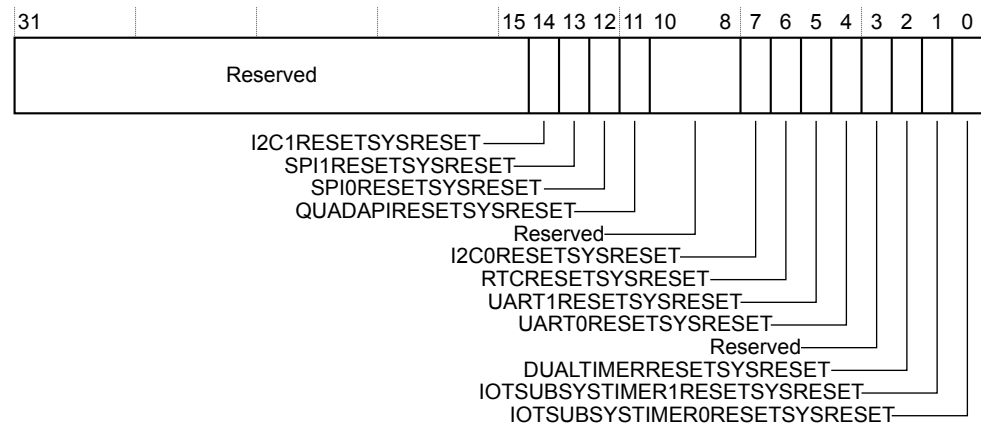


Figure 4-26 APBPRST0CLR Register bit assignments

The following table shows the bit assignments.

Table 4-31 APBPRST0CLR Register bit assignments

Bits	Name	Function
[31:15]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[14]	I2C1RESETSYSRESET	<p>0b0 No effect.</p> <p>0b1 Selects system reset as the reset signal for the I2C1 peripheral.</p>
[13]	SPI1RESETSYSRESET	<p>0b0 No effect.</p> <p>0b1 Selects system reset as the reset signal for the SPI1 peripheral.</p>
[12]	SPI0RESETSYSRESET	<p>0b0 No effect.</p> <p>0b1 Selects system reset as the reset signal for the SPI0 peripheral.</p>
[11]	QUADSPICRESETSYSRESET	<p>0b0 No effect.</p> <p>0b1 Selects system reset as the reset signal for the QUADSPI.</p>
[10:8]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[7]	I2C0RESETSYSRESET	<p>0b0 No effect.</p> <p>0b1 Selects system reset as the reset signal for the I2C0 peripheral.</p>
[6]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[5]	UART1RESETSYSRESET	<p>0b0 No effect.</p> <p>0b1 Selects system reset as the reset signal for UART1.</p>
[4]	UART0RESETSYSRESET	<p>0b0 No effect.</p> <p>0b1 Selects system reset as the reset signal for UART0.</p>
[3]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[2]	DUALTIMERRESETSYSRESET	<p>0b0 No effect.</p> <p>0b1 Selects system reset as the reset signal for the dual-timer.</p>

Table 4-31 APBPRST0CLR Register bit assignments (continued)

Bits	Name	Function
[1]	IOTSUBSYSTIMER1RESETSYSRESET	<p>0b0 No effect.</p> <p>0b1 Selects system reset as the reset signal for the IoT Compute subsystem timer 1.</p>
[0]	IOTSUBSYSTIMER0RESETSYSRESET	<p>0b0 No effect.</p> <p>0b1 Selects system reset as the reset signal for the IoT Compute subsystem timer 0.</p>

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.27 PWRDNCFG0SET

The PWRDNCFG0SET Register characteristics are:

Purpose

Enables sleep state wakeup signals for the AHB peripherals. This register has the same read value as PWRDNCFG0CLR.

Usage constraints

Bits [31:17], and bits [15:2] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

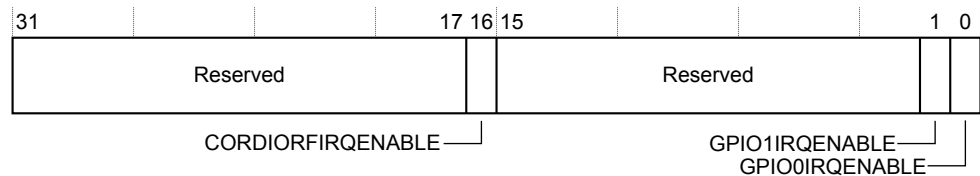


Figure 4-27 PWRDNCFG0SET Register bit assignments

The following table shows the bit assignments.

Table 4-32 PWRDNCFG0SET Register bit assignments

Bits	Name	Function
[31:17]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[16]	CORDIORFIRQENABLE	<p>0b0 No effect.</p> <p>0b1 Enables Cordio BT4 RF block IRQ as wakeup source.</p>
[15:2]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.

Table 4-32 PWRDNCFG0SET Register bit assignments (continued)

Bits	Name	Function
[1]	GPIO1IRQENABLE	0b0 No effect. 0b1 Enables GPIO1 IRQ as wakeup source.
[0]	GPIO0IRQENABLE	0b0 No effect. 0b1 Enables GPIO0 IRQ as wakeup source.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.28 PWRDNCFG0CLR

The PWRDNCFG0CLR Register characteristics are:

Purpose

Disables sleep state wakeup signals for the AHB peripherals. This register has the same read value as PWRDNCFG0SET.

Usage constraints

Bits [31:17], and bits [15:2] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

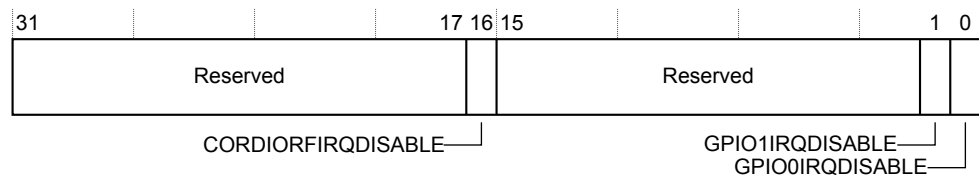


Figure 4-28 PWRDNCFG0CLR Register bit assignments

The following table shows the bit assignments.

Table 4-33 PWRDNCFG0CLR Register bit assignments

Bits	Name	Function
[31:17]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[16]	CORDIORFIRQDISABLE	0b0 No effect. 0b1 Disables Cordio BT4 RF block IRQ as wakeup source.
[15:2]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.

Table 4-33 PWRDNCFG0CLR Register bit assignments (continued)

Bits	Name	Function
[1]	GPIO1IRQDISABLE	0b0 No effect. 0b1 Disables GPIO1 IRQ as wakeup source.
[0]	GPIO0IRQDISABLE	0b0 No effect. 0b1 Disables GPIO0 IRQ as wakeup source.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.29 PWRDNCFG1SET

The PWRDNCFG1SET Register characteristics are:

Purpose

Enables sleep state wakeup signals for the APB peripherals. This register has the same read value as PWRDNCFG1CLR.

Usage constraints

Bits [31:15], bits [10:9], and bit [3] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

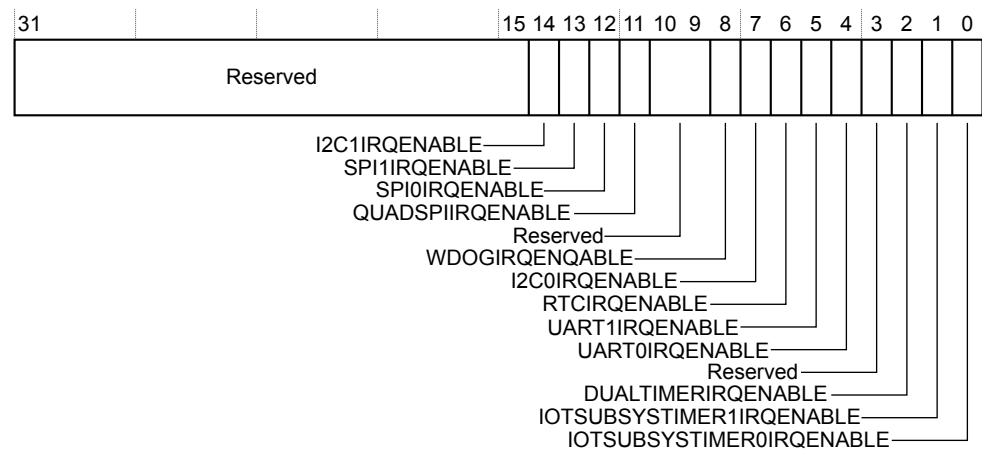


Figure 4-29 PWRDNCFG1SET Register bit assignments

The following table shows the bit assignments.

Table 4-34 PWRDNCFG1SET Register bit assignments

Bits	Name	Function
[31:15]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[14]	I2C1IRQENABLE	0b0 No effect. 0b1 Enables I2C1 IRQ as wakeup source.

Table 4-34 PWRDNCFG1SET Register bit assignments (continued)

Bits	Name	Function
[13]	SPI1IRQENABLE	0b0 No effect. 0b1 Enables SPI1 IRQ as wakeup source.
[12]	SPI0IRQENABLE	0b0 No effect. 0b1 Enables SPI0 IRQ as wakeup source.
[11]	QUADSPICIRQENABLE	0b0 No effect. 0b1 Enables QUADSPI IRQ as wakeup source.
[10:9]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[8]	WDOGIRQENABLE	0b0 No effect. 0b1 Enables Watchdog IRQ as wakeup source.
[7]	I2C0IRQENABLE	0b0 No effect. 0b1 Enables I2C0 IRQ as wakeup source.
[6]	RTCIRQENABLE	0b0 No effect. 0b1 Enables RTC IRQ as wakeup source.
[5]	UART1IRQENABLE	0b0 No effect. 0b1 Enables UART1 IRQ as wakeup source.
[4]	UART0IRQENABLE	0b0 No effect. 0b1 Enables UART0 IRQ as wakeup source.
[3]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[2]	DUALTIMERIRQENABLE	0b0 No effect. 0b1 Enables dual-timer IRQ as wakeup source.
[1]	IOTSUBSYSTEMTIMER1IRQENABLE	0b0 No effect. 0b1 Enables IoT Compute subsystem time1 IRQ as wakeup source.
[0]	IOTSUBSYSTEMTIMER0IRQENABLE	0b0 No effect. 0b1 Enables IoT Compute subsystem timer 0 IRQ as wakeup source.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.30 PWRDNCFG1CLR

The PWRDNCFG1CLR Register characteristics are:

Purpose

Disables sleep state wakeup signals for the APB peripherals. This register has the same read value as PWRDNCFG1SET.

Usage constraints

Bits [31:15], bits [10:9], and bit [3] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

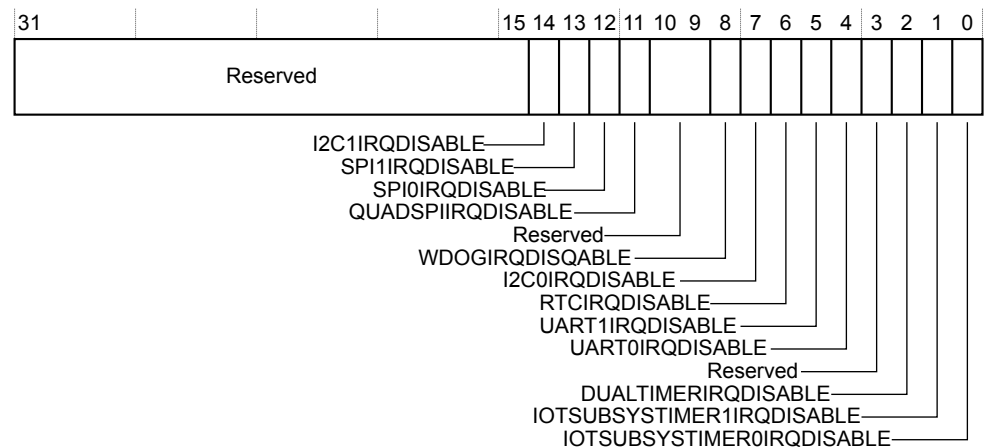


Figure 4-30 PWRDNCFG1CLR Register bit assignments

The following table shows the bit assignments.

Table 4-35 PWRDNCFG1CLR Register bit assignments

Bits	Name	Function
[31:15]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[14]	I2C1IRQDISABLE	0b0 No effect. 0b1 Disables I2C1 IRQ as wakeup source.
[13]	SPI1IRQDISABLE	0b0 No effect. 0b1 Disables SPI1 IRQ as wakeup source.
[12]	SPI0IRQDISABLE	0b0 No effect. 0b1 Disables SPI0 IRQ as wakeup source.
[11]	QUADSPICIRQDISABLE	0b0 No effect. 0b1 Disables QUADSPI IRQ as wakeup source.
[10:9]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[8]	WDOGIRQDISABLE	0b0 No effect. 0b1 Disables Watchdog IRQ as wakeup source.

Table 4-35 PWRDNCFG1CLR Register bit assignments (continued)

Bits	Name	Function
[7]	I2C0IRQDISABLE	0b0 No effect. 0b1 Disables I2C0 IRQ as wakeup source.
[6]	RTCIRQDISABLE	0b0 No effect. 0b1 Disables RTC IRQ as wakeup source.
[5]	UART1IRQDISABLE	0b0 No effect. 0b1 Disables UART1 IRQ as wakeup source.
[4]	UART0IRQDISABLE	0b0 No effect. 0b1 Disables UART0 IRQ as wakeup source.
[3]	-	Reserved. Software that writes to this register must write zero to this bit. Software that reads this register must ignore this bit.
[2]	DUALTIMERIRQDISABLE	0b0 No effect. 0b1 Disables dual-timer IRQ as wakeup source.
[1]	IOTSUBSYSTEMTIMER1IRQDISABLE	0b0 No effect. 0b1 Disables IoT Compute subsystem timer1 IRQ as wakeup source.
[0]	IOTSUBSYSTEMTIMER0IRQDISABLE	0b0 No effect. 0b1 Disables IoT Compute subsystem timer 0 IRQ as wakeup source.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.31 RTCRESET

The RTCRESET Register characteristics are:

Purpose

Resets the real-time clock.

Usage constraints

Bits [31:1] are reserved. Bit [0] is write-only.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

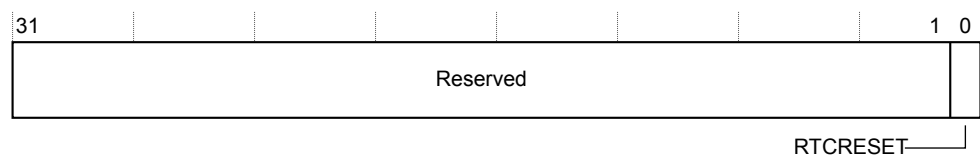


Figure 4-31 RTCRESET Register bit assignments

The following table shows the bit assignments.

Table 4-36 RTCRESET Register bit assignments

Bits	Name	Function
[31:1]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[0]	RTCRESET	Resets the real-time clock, 1Hz domain, to zero.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.32 EVENTCFG

The EVENTCFG Register characteristics are:

Purpose

Controls the event interface.

Usage constraints

Bits [31:2] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

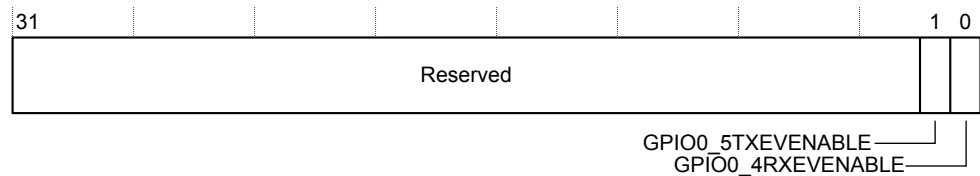


Figure 4-32 EVENTCFG Register bit assignments

The following table shows the bit assignments.

Table 4-37 EVENTCFG Register bit assignments

Bits	Name	Function
[31:2]	-	Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[1]	GPIO0_5TXEVENABLE	0b0 No effect. 0b1 Enables GPIO0[5] TXEV.
[0]	GPIO0_4RXEVENABLE	0b0 No effect. 0b1 Enables GPIO0[4] RXEV.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.33 PWROVRIDE0

The PWROVRIDE0 Register characteristics are:

Purpose

Controls the SRAM power control override signals.

Usage constraints

Bits [31:6] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

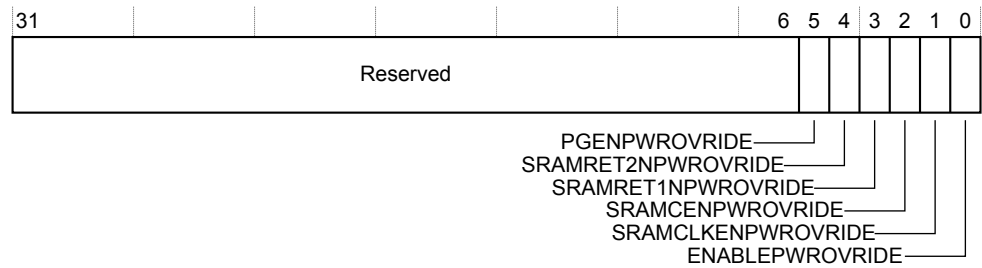


Figure 4-33 PWROVERRIDE0 Register bit assignments

The following table shows the bit assignments.

Table 4-38 PWROVERRIDE0 Register bit assignments

Bits	Name	Function
[31:6]		Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[5]	PGENPWROVERRIDE	When enabled by bit [0], controls RAM power control signal PGEN : Bit [0] = 0b0 Bit [5] has no effect. PMU controls PGEN . Bit [0] = 0b1 Bit [5] overrides RAM power control signal PGEN , that is, PGEN = bit [5].
[4]	SRAMRET2NPWROVERRIDE	When enabled by bit [0], controls RAM power control signal SRAMRET2N : Bit [0] = 0b0 Bit [4] has no effect. PMU controls SRAMRET2N . Bit [0] = 0b1 Bit [4] overrides PMU RAM power control signal SRAMRET2N , that is, SRAMRET2N = bit [4].
[3]	SRAMRET1NPWROVERRIDE	When enabled by bit [0], controls RAM power control signal SRAMRET1N : Bit [0] = 0b0 Bit [3] has no effect. PMU controls SRAMRET1N . Bit [0] = 0b1 Bit [3] overrides PMU RAM power control signal SRAMRET1N , that is, SRAMRET1N = bit [3].

Table 4-38 PWROVRIDE0 Register bit assignments (continued)

Bits	Name	Function
[2]	SRAMCENPWROVRIDE	When enabled by bit [0], controls RAM control signal SRAMCEN : Bit [0] = 0b0 Bit [2] has no effect. PMU controls SRAMCEN . Bit [0] = 0b1 Bit [2] overrides PMU RAM control signal SRAMCEN , that is, SRAMCEN = bit [2].
[1]	SRAMCLKENPWROVRIDE	When enabled by bit [0], controls RAM clock enable signal SRAMCLKEN : Bit [0] = 0b0 Bit [1] has no effect. PMU controls SRAMCLKEN . Bit [0] = 0b1 Bit [1] overrides PMU RAM clock enable signal SRAMCLKEN , that is, SRAMCLKEN = bit [1].
[0]	ENABLEPWROVRIDE	0b0 Disables power control override signals, bits [5:1], in this register. PMU controls RAM power control signals. 0b1 Enables power control override signals in this register. Disables PMU RAM power control signals.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.34 PWROVRIDE1

The PWROVRIDE1 Register characteristics are:

Purpose

Controls the eFlash power control override signals.

Usage constraints

Bits [31:9] are reserved.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

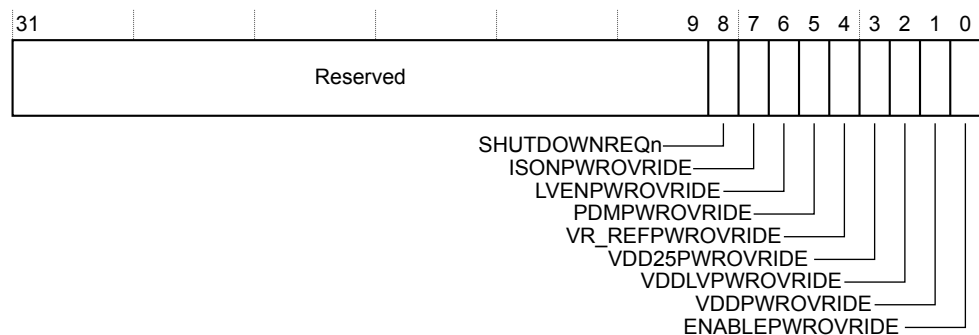


Figure 4-34 PWROVRIDE1 Register bit assignments

The following table shows the bit assignments.

Table 4-39 PWROVERRIDE1 Register bit assignments

Bits	Name	Function
[31:9]		Reserved. Software that writes to this register must write all zeros to these bits. Software that reads this register must ignore these bits.
[8]	SHUTDNREQnPWROVERRIDE	When enabled by bit [0], controls eFlash power control signal SHUTDNREQn . Bit [0] = 0b0 Bit [8] has no effect. Bit [0] = 0b1 Bit [8] overrides eFlash shutdown request signal SHUTDNREQn , that is, SHUTDNREQn = bit [8].
[7]	ISONPWROVERRIDE	When enabled by bit [0], controls eFlash power control signal ISOn that isolates the eFlash signals from other parts of the test chip. Bit [0] = 0b0 Bit [7] has no effect. PMU controls ISOn . Bit [0] = 0b1 Bit [7] overrides eFlash power control signal ISOn , that is, ISOn = bit [7].
[6]	LVENPWROVERRIDE	When enabled by bit [0], controls eFlash power control signal LVEN . Bit [0] = 0b0 Bit [6] has no effect. PMU controls LVEN . Bit [0] = 0b1 Bit [6] overrides eFlash power control signal LVEN , that is, LVEN = bit [6].
[5]	PDMPWROVERRIDE	When enabled by bit [0], controls eFlash power control signal PDM . Bit [0] = 0b0 Bit [5] has no effect. PMU controls PDM . Bit [0] = 0b1 Bit [5] overrides eFlash PDM power control signal PDM , that is, PDM = bit [5].
[4]	VR_REFPWROVERRIDE	When enabled by bit [0], controls eFlash power control signal VR_REF . Bit [0] = 0b0 Bit [4] has no effect. PMU controls VR_REF . Bit [0] = 0b1 Bit [4] overrides eFlash VR_REF power control signal VR_REF , that is, VR_REF = bit [4].
[3]	VDD25PWROVERRIDE	When enabled by bit [0], controls eFlash power control signal VDD25 . Bit [0] = 0b0 Bit [3] has no effect. PMU controls VDD25 . Bit [0] = 0b1 Bit [3] overrides eFlash 2V5 power control signal VDD25 , that is, VDD25 = bit [3].

Table 4-39 PWROVERRIDE1 Register bit assignments (continued)

Bits	Name	Function
[2]	VDDLVPWROVERRIDE	When enabled by bit [0], controls eFlash power control signal VDDL . Bit [0] = 0b0 Bit [2] has no effect. PMU controls VDDL . Bit [0] = 0b1 Bit [2] overrides eFlash 3V3 power control signal VDDL , that is, VDDL = bit [2].
[1]	VDDPWROVERRIDE	When enabled by bit [0], controls eFlash power control signal VDD . Bit [0] = 0b0 Bit [1] has no effect. PMU controls VDD . Bit [0] = 0b1 Bit [1] overrides eFlash VDD power control signal VDD , that is, VDD = bit [1].
[0]	ENABLEPWROVERRIDE	0b0 Disables power control override signals, bits [8:1], in this register. PMU controls eFlash power control signals 0b1 Enables power control override signals, bits [8:1], in this register. Disables PMU eFlash power control signals

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.35 PID4

The PID4 Register characteristics are:

Purpose

Stores peripheral identification information.

Usage constraints

This register is read-only.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

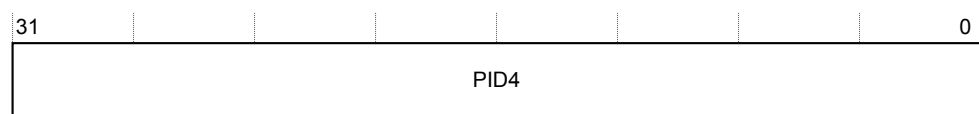


Figure 4-35 PID4 Register bit assignments

The following table shows the bit assignments.

Table 4-40 PID4 Register bit assignments

Bits	Name	Function
[31:0]	PID4	Peripheral ID 4 identification. The value on the test chip r0p0 is 0x0004.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.36 PID5

The PID5 Register characteristics are:

Purpose

Stores peripheral identification information.

Usage constraints

This register is read-only.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

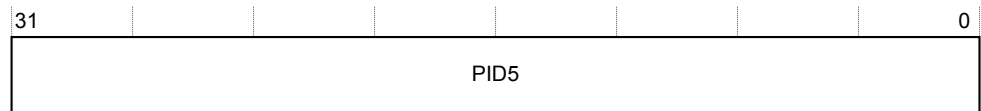


Figure 4-36 PID5 Register bit assignments

The following table shows the bit assignments.

Table 4-41 PID5 Register bit assignments

Bits	Name	Function
[31:0]	PID5	Peripheral ID 5 identification. The value on the test chip r0p0 is 0x0000.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.37 PID6

The PID6 Register characteristics are:

Purpose

Stores peripheral identification information.

Usage constraints

This register is read-only.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

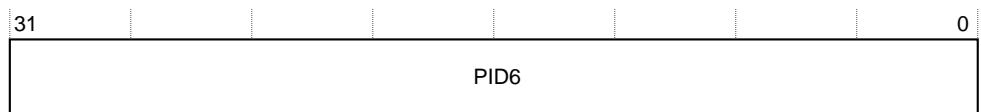


Figure 4-37 PID6 Register bit assignments

The following table shows the bit assignments.

Table 4-42 PID6 Register bit assignments

Bits	Name	Function
[31:0]	PID6	Peripheral ID 6 identification. The value on the test chip r0p0 is 0x0000.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.38 PID7

The PID7 Register characteristics are:

Purpose

Stores peripheral identification information.

Usage constraints

This register is read-only.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

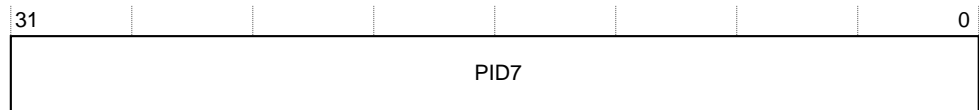


Figure 4-38 PID7 Register bit assignments

The following table shows the bit assignments.

Table 4-43 PID7 Register bit assignments

Bits	Name	Function
[31:0]	PID7	Peripheral ID 7 identification. The value on the test chip r0p0 is 0x0000.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.39 PID0

The PID0 Register characteristics are:

Purpose

Stores peripheral identification information.

Usage constraints

This register is read-only.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

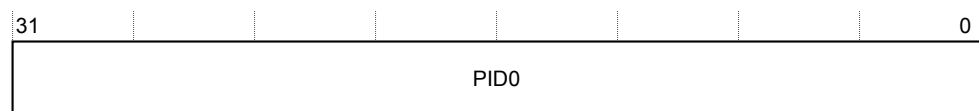


Figure 4-39 PID0 Register bit assignments

The following table shows the bit assignments.

Table 4-44 PID0 Register bit assignments

Bits	Name	Function
[31:0]	PID0	Peripheral ID 0 identification. The value on the test chip r0p0 is 0x0042.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.40 PID1

The PID1 Register characteristics are:

Purpose

Stores peripheral identification information.

Usage constraints

This register is read-only.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

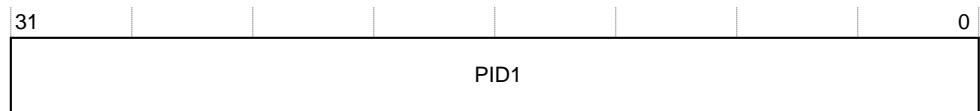


Figure 4-40 PID1 Register bit assignments

The following table shows the bit assignments.

Table 4-45 PID1 Register bit assignments

Bits	Name	Function
[31:0]	PID1	Peripheral ID 1 identification. The value on the test chip r0p0 is 0x00B7.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.41 PID2

The PID2 Register characteristics are:

Purpose

Stores peripheral identification information.

Usage constraints

This register is read-only.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

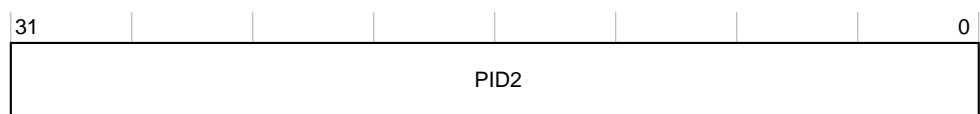


Figure 4-41 PID2 Register bit assignments

The following table shows the bit assignments.

Table 4-46 PID2 Register bit assignments

Bits	Name	Function
[31:0]	PID2	Peripheral ID 2 identification. The value on the test chip is 0x00rB where r is the revision number.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.42 PID3

The PID3 Register characteristics are:

Purpose

Stores peripheral identification information.

Usage constraints

This register is read-only.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

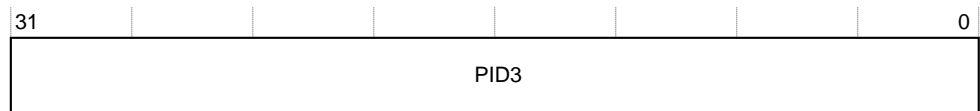


Figure 4-42 PID3 Register bit assignments

The following table shows the bit assignments.

Table 4-47 PID3 Register bit assignments

Bits	Name	Function
[31:0]	PID3	Peripheral ID 3 identification. The value on the test chip r0p0 is 0x0000.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.43 CID0

The CID0 Register characteristics are:

Purpose

Stores component identification information.

Usage constraints

This register is read-only.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

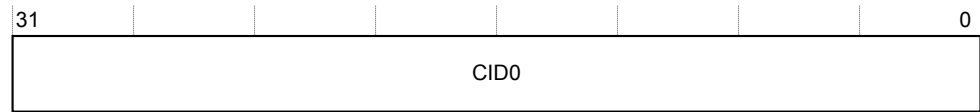


Figure 4-43 CID0 Register bit assignments

The following table shows the bit assignments.

Table 4-48 CID0 Register bit assignments

Bits	Name	Function
[31:0]	CID0	Component ID 0 identification. The value on the test chip r0p0 is 0x000D.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.44 CID1

The CID1 Register characteristics are:

Purpose

Stores component identification information.

Usage constraints

This register is read-only.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

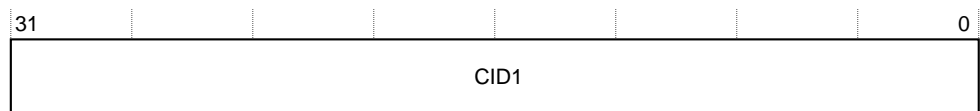


Figure 4-44 CID1 Register bit assignments

The following table shows the bit assignments.

Table 4-49 CID1 Register bit assignments

Bits	Name	Function
[31:0]	CID1	Component ID 1 identification. The value on the test chip r0p0 is 0x0010.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.45 CID2

The CID2 Register characteristics are:

Purpose

Stores component identification information.

Usage constraints

This register is read-only.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

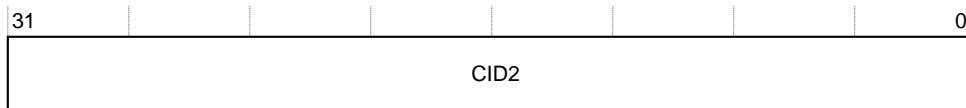


Figure 4-45 CID2 Register bit assignments

The following table shows the bit assignments.

Table 4-50 CID1 Register bit assignments

Bits	Name	Function
[31:0]	CID2	Component ID 2 identification. The value on the test chip r0p0 is 0x0005.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

4.7.46 CID3

The CID3 Register characteristics are:

Purpose

Stores component identification information.

Usage constraints

This register is read-only.

Configurations

Available in all V2M-Beetle evaluation board configurations.

The following figure shows the bit assignments.

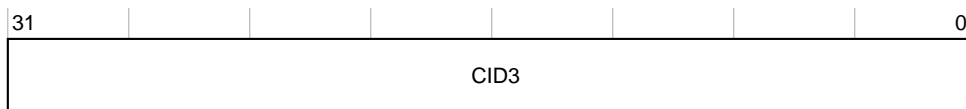


Figure 4-46 CID3 Register bit assignments

The following table shows the bit assignments.

Table 4-51 CID1 Register bit assignments

Bits	Name	Function
[31:0]	CID3	Component ID 3 identification. The value on the test chip r0p0 is 0x00B1.

Related concepts

[4.7.1 System control register summary on page 4-64.](#)

Appendix A.1

Signal Descriptions

This appendix describes the signals present at the interface connectors of the V2M-Beetle evaluation board.

It contains the following sections:

- [A.1.1 Arduino interface connectors](#) on page Appx-A-118.
- [A.1.2 ICSP connector](#) on page Appx-A-122.
- [A.1.3 USB connector](#) on page Appx-A-123.
- [A.1.4 Debug connector](#) on page Appx-A-124.

A.1.1 Arduino interface connectors

The V2M-Beetle evaluation board provides four header connectors to enable the fitting of an Arduino-compatible R3 expansion shield.

This section contains the following subsections:

- [Arduino AD connector on page Appx-A-118.](#)
- [Arduino IOH connector on page Appx-A-118.](#)
- [Arduino IOL connector on page Appx-A-119.](#)
- [Arduino power connector on page Appx-A-120.](#)

Arduino AD connector

The V2M-Beetle evaluation board provides one Arduino Analog connector.

The Arduino Analog connector carries six Analog signals from the expansion shield to the ADC on the V2M-Beetle evaluation board.

The following figure shows the Arduino Analog connector.

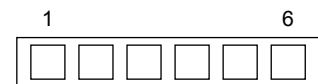


Figure A-1 Arduino Analog connector

The following table shows the pin mapping for the signals on the Arduino Analog connector.

Table A-1 Arduino Analog connector, J6, signal list

Pin	Signal
1	A5
2	A4
3	A3
4	A2
5	A1
6	A0

Related references

[1.5 Location of components on the V2M-Beetle evaluation board on page 1-16.](#)

Arduino IOH connector

The V2M-Beetle evaluation board provides one Arduino I/O High (IOH) connector.

The Arduino IOH connector carries the following signals between the expansion shield and the test chip on the board:

- GPIO0.
- Multiplexed GPIO0/SPI0.
- Multiplexed GPIO0/I2C0.

The Arduino IOH connector also carries the voltage reference from the expansion shield to the ADC on the board.

The following figure shows the Arduino IOH connector.

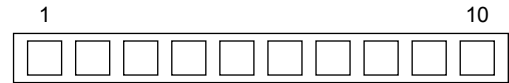


Figure A-2 Arduino I/O High (IOH) connector

The following table shows the pin mapping for the signals on the Arduino IOH connector.

Table A-2 Arduino I/O High (IOH) connector, J3, signal list

Pin	Signal	Description
1	GPIO0[8]	-
2	GPIO0[9]	-
3	Multiplexed GPIO0[10]/SPI0 nSS	-
4	Multiplexed GPIO0[11]/SPI0 MOSI (Out)	This signal is shared with the Arduino ICSP connector.
5	Multiplexed GPIO0[12]/SPI0 MISO (In)	This signal is shared with the Arduino ICSP connector.
6	Multiplexed GPIO0[13]/SPI0 SCK (Out)	This signal is shared with the Arduino ICSP connector.
7	GND	-
8	AVREF	-
9	Multiplexed GPIO0[14]/I2C0 Data (SDA)	-
10	Multiplexed GPIO0[15]/I2C0 Clock (SCL)	-

Note

Pin 9 and 10 have 10k pullup resistors to the **IOREF** voltage. See [Arduino power connector on page Appx-A-120](#).

Related concepts

- [2.3 Beetle test chip GPIO interface on page 2-24.](#)
- [4.6 GPIO registers on page 4-58.](#)
- [2.7 SPI ADC interface on page 2-32.](#)

Related references

- [1.5 Location of components on the V2M-Beetle evaluation board on page 1-16.](#)

Arduino IOL connector

The V2M-Beetle evaluation board provides one Arduino I/O Low (IOL) connector.

The Arduino IOL connector carries the following signals between the expansion shield and the test chip on the board:

- GPIO0.
- Multiplexed GPIO0/UART0.
- Multiplexed GPIO0/nNMI.
- Multiplexed GPIO0/timer.

The following figure shows the Arduino IOL connector.

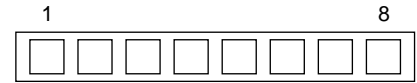


Figure A-3 Arduino I/O Low (IOL) connector

The following table shows the pin mapping for the signals on the Arduino IOL connector.

Table A-3 Arduino I/O Low (IOL) connector, J7, signal list

Pin	Signal	Description
1	Multiplexed GPIO0[0]/UART0 RxD (In)	-
2	Multiplexed GPIO0[1]/UART0 TxD (Out)	-
3	GPIO0[2]	-
4	Multiplexed GPIO0[3]/nNMI.	When the nNMI is selected, it is OR-ed with the Watchdog input and connected to the Cortex-M3 NMI input.
5	Multiplexed GPIO0[4]/Timer 0 input.	The multiplexed timer signals are alternative inputs for the timers in the IoT Compute subsystem
6	Multiplexed GPIO0[5]/Timer 1 input.	
7	GPIO0[6]	-
8	GPIO0[7]	-

The GPIO registers select the multiplexed signals.

Related concepts

[2.3 Beetle test chip GPIO interface on page 2-24.](#)

[4.6 GPIO registers on page 4-58.](#)

Related references

[1.5 Location of components on the V2M-Beetle evaluation board on page 1-16.](#)

Arduino power connector

The V2M-Beetle evaluation board provides one Arduino power connector.

The Arduino power connector carries power supplies, and an I/O reference voltage to the expansion shield. It also carries a bidirectional reset signal between the V2M-Beetle evaluation board and the expansion shield.

The following figure shows the Arduino power connector.

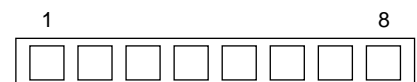


Figure A-4 Arduino power connector

The following table shows the pin mapping for the signals on the Arduino power connector.

Table A-4 Arduino power connector, J4, signal list

Pin	Signal	Description
1	No connection	-
2	IOREF	I/O reference voltage for expansion shield. ————— Note ————— This pin is bidirectional. The pin can accept an input voltage of up to 5V. The output voltage is always 3V3. —————
3	nRESET	This signal also connects to nRESET on the Arduino ICSP connector.
4	VCC_3V3	Power source to expansion shield.
5	VCC_5V	Power source to expansion shield.
6	GND	-
7	GND	-
8	No connection	No connection because the board does not support powering from the VIN pin.

Related references

1.5 Location of components on the V2M-Beetle evaluation board on page 1-16.

A.1.2 ICSP connector

The V2M-Beetle evaluation board provides ICSP connector to enable In-Circuit Serial Programming.

The ICSP connector carries three of the GPIO signals on the Arduino IOH connector. The signals function as SPI signals on the ICSP connector.

The following figure shows the ICSP connector.

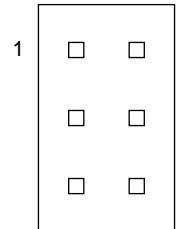


Figure A-5 ICSP connector

The following table shows the pin mapping for the signals on the ICSP connector.

Table A-5 ICSP connector, J15, signal list

Pin	Signal	Description
1	SPI MISO (In)	This signal is GPIO[12] from the Beetle test chip and is shared with the Arduino IOH connector.
2	5V	-
3	SPI SCK (Out)	This signal is GPIO[13] from the Beetle test chip and is shared with the Arduino IOH connector.
4	SPI MOSI (Out)	This signal is GPIO[11] from the Beetle test chip and is shared with the Arduino IOH connector.
5	nRESET	This signal also connects to nRESET on the Arduino power connector.
6	GND	-

Related references

[1.5 Location of components on the V2M-Beetle evaluation board on page 1-16.](#)

A.1.3 USB connector

The V2M-Beetle evaluation board provides one mini-B USB connector.

The USB connector enables CMSIS-DAP debug over USB, and external 5V power to the board.

The following figure shows the USB connector.

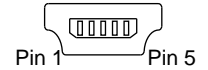


Figure A-6

The following table shows the pin mapping for the signals on the USB connector.

Table A-6 USB mini-B connector, J30, signal list

Pin	Signal	Pin	Signal
1	5V	2	DATA-
3	DATA+	4	ID
5	GND	6	GND_EARTH

Note

The **GND_EARTH** connection is the casing of the mini-B connector.

Related concepts

[2.6 USB interface on page 2-30.](#)

Related references

[1.5 Location of components on the V2M-Beetle evaluation board on page 1-16.](#)

A.1.4 Debug connector

The V2M-Beetle evaluation board provides one ARM CoreSight™ debug and ETM 20-pin connector.

The connector enables Serial Wire Debug (SWD), 4-bit trace, and P-JTAG debug.

The following figure shows debug connector.

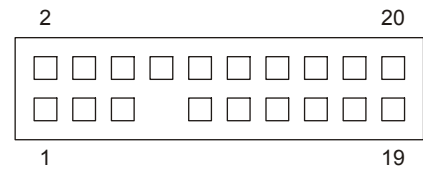


Figure A-7 Debug connector

The following table shows the pin mapping for the signals on the debug connector.

Table A-7 Debug connector, J16, signal list

Pin	Signal	Pin	Signal
1	VTREF	2	SWDIO/TMS
3	GND	4	SWDCLK/TCK
5	GND	6	SWO/TDO
7	-	8	GND
9	GND	10	nRESET
11	Reserved	12	GND
13	Reserved	14	SWO/TRACEDATA[0]
15	GND	16	nTRST/TRACEDATA[1]
17	GND	18	DBGREQ/TRACEDATA[2]
19	GND	20	DBGACK/TRACEDATA[3]

Related concepts

[2.13 Debug and trace on page 2-40.](#)

Related references

[1.5 Location of components on the V2M-Beetle evaluation board on page 1-16.](#)

Appendix B.2

Specifications

This specification contains the electrical specifications of the V2M-Beetle evaluation board.

It contains the following sections:

- [B.2.1 Specifications on page Appx-B-126.](#)

B.2.1 Specifications

The following table contains electrical operating information for the V2M-Beetle evaluation board.

Appendix C.3

Revisions

This appendix describes the technical changes between released issues of this book.

It contains the following sections:

- [C.3.1 Revisions on page Appx-C-128](#).

C.3.1 Revisions

The following tables describe technical changes between released issues of this book.

Table C-1 Issue 0000-00

Change	Location	Affects
No changes, first release	-	-